OFM

Internals of Docking Storage with Kubernetes Workloads

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Agenda

- Background
- What's CSI
- CSI vs FlexVolume
- How CSI works
- FlexVolume Driver Part

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• CSI Driver Part

Background

- 1. Kubernetes has supported a long list of volume types such as:
 - awsElasticBlockStore
 - fc(fibre channel)
 - scaleIO
 - list to be continued...

Those are so-called `In-tree` volume plugins.

2. Even k8s has do a lot for you, but sometimes you still need to write a new one.

In this case, FlexVolume and CSI can help you well ③ which is also the focus of our today's topic: Out-of-Tree volume plugin interface.

Background

- 1. In-tree Volume Plugins
 - Those are linked, compiled, built and shipped with the core k8s binaries
 - Development is tightly coupled and dependent on k8s releases
 - Bugs in volume plugin can crash critical k8s components, instead of just the plugin
 - <u>Will not be accepted since k8s 1.8</u>
- 2. Out-of-Tree Volume Plugins (customized plugins by storage providers)
 - FlexVolume driver
 - CSI driver (*)



- Container Storage Interface (CSI) is a standardized mechanism for Container Orchestration Systems (COs), including Kubernetes, to expose arbitrary storage systems to containerized workloads. Storage Provider (SP) develops once and this works across a number of COs.
- The goal of CSI is to become the primary volume plugin system for k8s in the future.
- k8s 1.9 release has already included the alpha feature of CSI implementation, then beta in Kubernetes v1.10
- The CSI spec can be found at:

https://github.com/container-storage-interface/spec/blob/master/spec.md

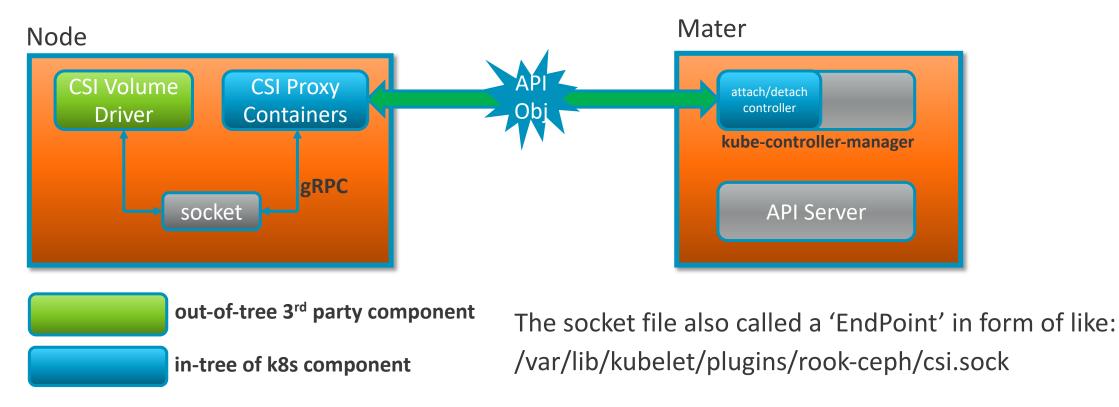
CSI vs FlexVolume

Two Out-of-Tree Volume Plugin mechanisms in K8s – FlexVolume and CSI

- 1. FlexVolume plugin framework:
 - Makes the 3rd party storage providers' plugin as "Out-of-Tree" (same as CSI does)
 - exec based API for external volume plugins
 - Needs to access the root filesystem of node and master machines when deploying
 - Doesn't address the pain point of dependencies.
- 2. CSI overcomes the limitations of FlexVolume listed above. CSI is the preferred solution, for now CSI and FlexVolume can co-exist.

How CSI works

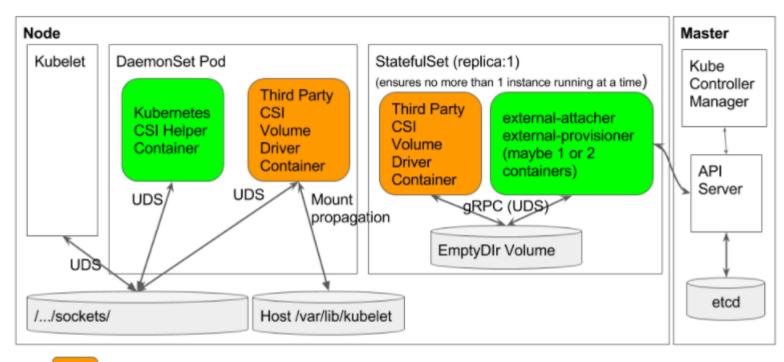
- A new in-tree CSI Volume plugin(K8s) + out-of-tree CSI Volume driver (3rd party)
- Communication channel via a Unix Domain Socket(UDS) created by 3rd Volume Driver





How CSI works

Recommended Mechanism for Deploying CSI Drivers on k8s

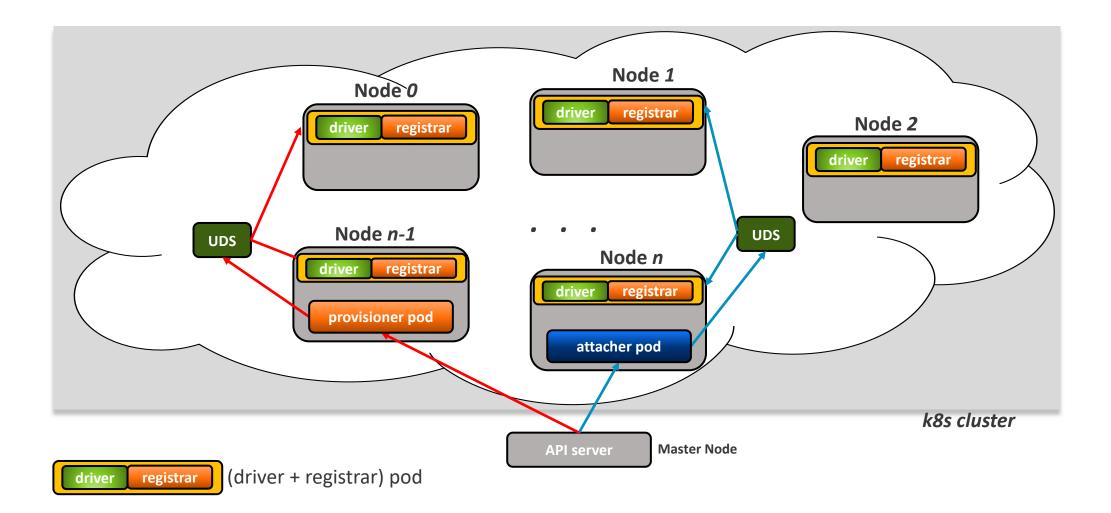


External Component - Created by Third Party Storage Vendor

External Component - Created by Kubernetes Team

https://github.com/kubernetes/community/blob/master/contributors/design-proposals/storage/container-storage-interface.md

A CSI deployment in real world



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FlexVolume Driver Part (Take Rook as an example)



FlexVolume Driver -- rookflex

- `rookflex` exists in form of a binary file and has been deployed into volume-plugin-dir by Rook Agent on each node.
- `rookflex` implements 'mount' and 'umount' methods required by <u>FlexVolume Spec</u>
- For a specific YAML file of a workload, the storage related part looks like:

		Storage Provisioning
)		
10	apiVersion: storage.k8s.io/v1	apiVersion: v1
11	kind: StorageClass	kind: PersistentVolumeClaim
12	metadata:	metadata:
13	name: rook-ceph-block	name: wp-pv-claim
14	provisioner: ceph.rook.io/block	labels:
15	parameters:	app: wordpress
16	pool: replicapool	spec:
		22 storageClassName: rook-ceph-block
		23 accessModes:
		24 - ReadWriteOnce
		25 resources:
		26 requests:
		27 storage: 20Gi
		28

A practical FlexVolume driver -- rookflex

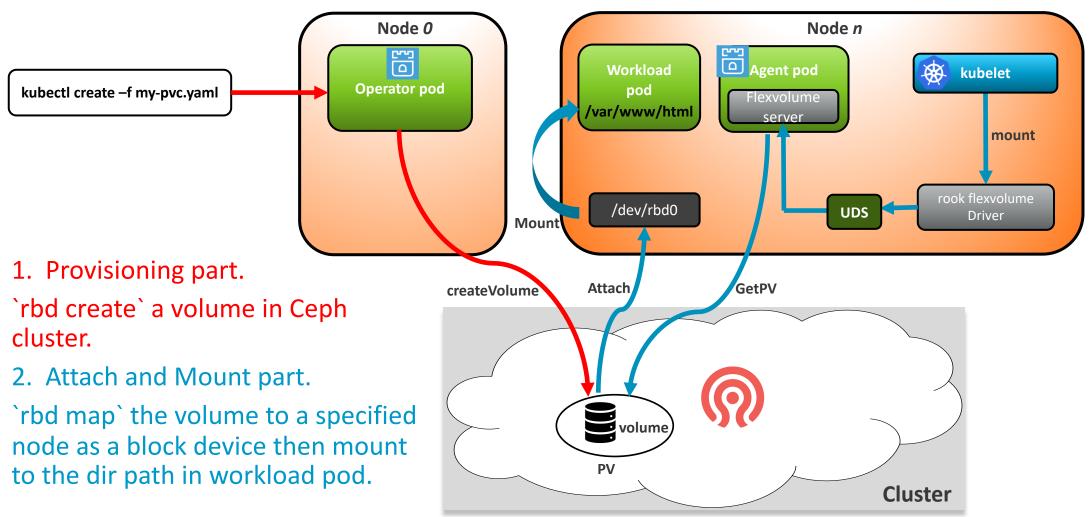
- When that workload pod is scheduled to one node and begin to run, the kubelet will interacts with the driver to mount the volume into the `mountPath` specified by the YAML. To do so, kubelet needs to:
 - 1. Lookup the right FlexVolume driver.

The look up flow is: PVC name \rightarrow StorageClass \rightarrow provisioner name: ceph.rook.io/block \rightarrow Flex volume vendor name: "ceph.rook.io" \rightarrow figure out the driver folder and driver name: rookflex

- 2. Call `mount` method of rookflex like: `\$(volume-plugin-dir)/rookflex mount`
- 3. The above `mount` will call the corresponding function in Rook Agent via UDS.
- 4. Local Rook Agent will attach the volume into its node(a 'rbd map' operation).

Flexvolume-based volume operations

kubectl create –f workload.yaml

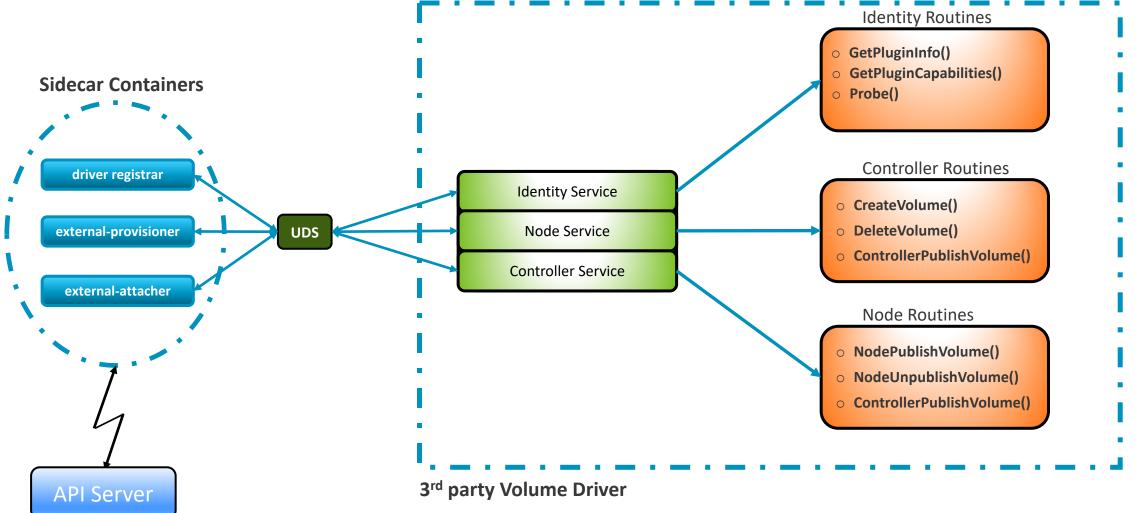


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CSI Volume Driver Part



CSI: Zoom into the volume driver

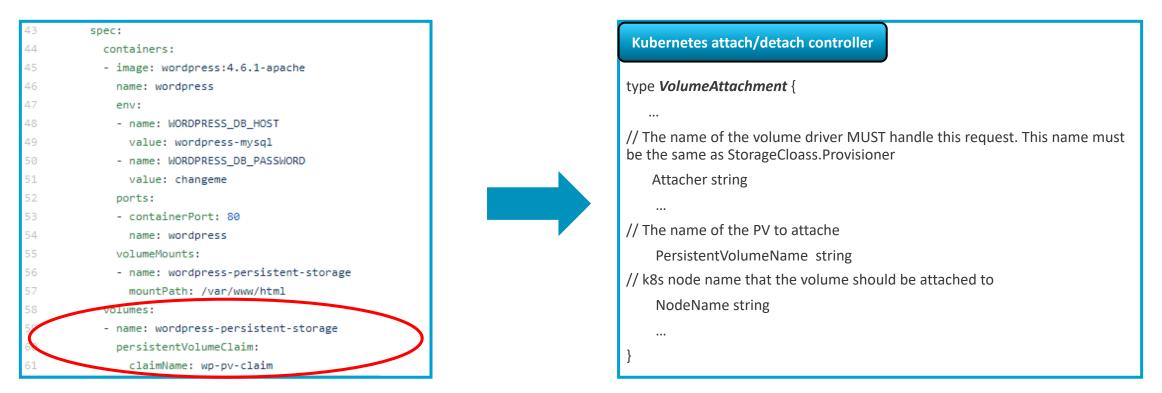




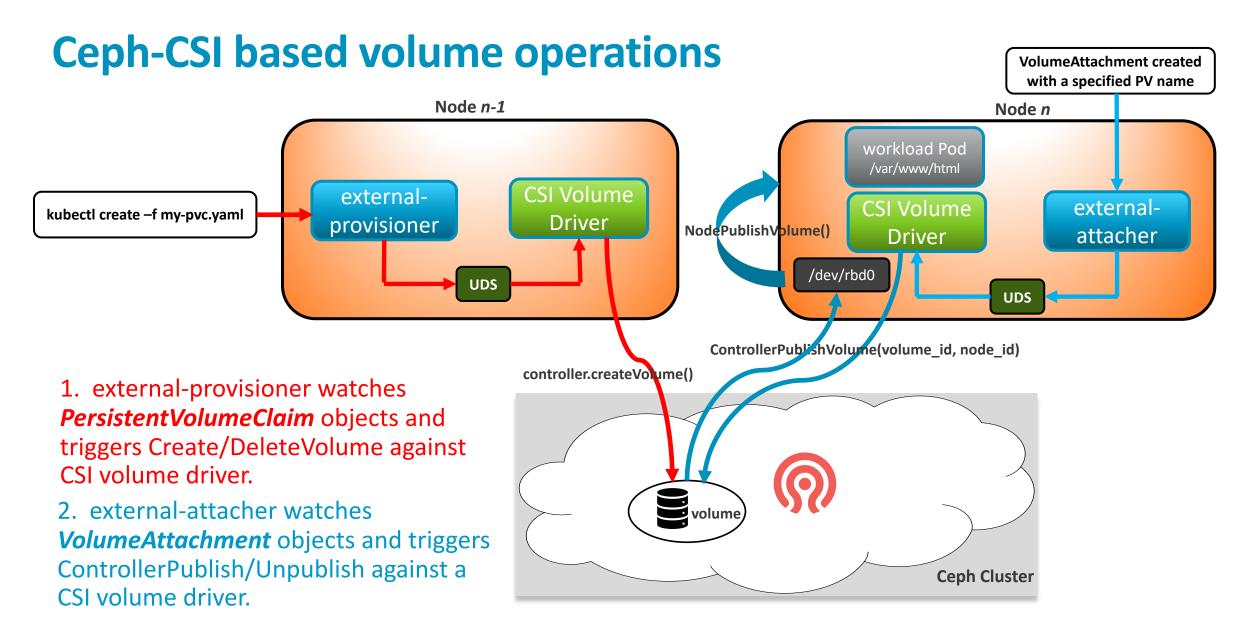
CSI: external-provisioner

- 1. A cluster admin creates a *StorageClass* pointing to the CSI driver's external-provisioner.
- 2. A user creates a *PersistantVolumeClaim* referring to the new *StorageClasss*.
- 3. The persistent volume controller realizes that dynamic provisioning is needed.
- 4. The external-provisioner for the CSI driver sees the *PersistentVolumeClaim* so it stats dynamic volume provisioning:
 - It deferences the *StorageClass* to collect the opaque parameters to use for provisioning.
 - It calls CreateVolume() against the CSI driver container with parameters from the *StorageClass* and *PersistentVolumeClaim* objects.
- 5. Once the volume is successfully created, the external-provisioner creates a *PersistentVolume* object to represent the newly create volume and binds it to the *PersistentVolumeClaim*.

CSI: external-attacher



- 1. k8s attach/detach controller sees that a pod referencing a CSI volume plugin is scheduled to a node → call in-tree volume plugin's attach()
- 2. The in-tree volume plugin creates a new VolumeAttachment object in the k8s API
- 3. The external-attacher sees the VolumeAttachment object and triggers a ControllerPublish again the CSI volume driver to fulfil it.



Thank You! Danke! Merci! 谢谢! ありがとう! **Gracias!** Kiitos!

