



**Embedded Linux  
Conference**

Europe



**OpenIoT Summit**  
Europe

# Port your camera in 2018

[jacopo@jmondi.org](mailto:jacopo@jmondi.org)

**Jacopo Mondì**  
**ELC-E 2018**  
**Edinburgh, 10/2018**



# Hello!

- My name's Jacopo
  - `jacopo@jmondi.org`
  - `irc: jmondi @ freenode`
- Embedded Linux and free software developer
- Working as consultant
- Renesas Electronics upstream kernel team

# Hello!

- Thanks Renesas for supporting me in this activity!



# Talk outline

- *soc\_camera*: what's happening?
- What has changed since the *soc\_camera* days:
  - Board files vs firmware support
  - Device discovery and linking
  - Power Management
- Practical example: *ov772x.c*
- Q/A

# The soc\_camera framework

- *soc\_camera* was GREAT
- Widely adopted
  - Mainline drivers
  - In BSPs and downstream kernel

# What's happening to soc\_camera

In mainline kernels:

- *soc\_camera* to be 'soon' deprecated (with 'soon' to be defined)
- Last *soc\_camera* dependent bridge driver has been re-implemented last year
- *soc\_camera* sensor drivers are not officially supported anymore

# What's happening to soc\_camera

## File organization:

- `drivers/media/platform/  
drivers/media/platform/soc_camera/`
- `drivers/media/i2c/  
drivers/media/i2c/soc_camera/`
- `drivers/media/i2c/mt9t112.c  
drivers/media/i2c/soc_camera/mt9t112.c`

# soc\_camera: the good

- Provides an abstraction to the crude V4L2 APIs
- Ease linking bridge drivers to sensor drivers
- Abstract driver operations to a structure of function pointers



# soc\_camera: the bad

- Designed for board-files:
  - OF and ACPI support is limited (hold on...)
- Use on a set of deprecated operations and frameworks
- Media-controller and subdev APIs are game changers
  - The single device node abstraction is showing its age...

# What has changed?

- device discovery and linking:
  - notifier(s) and async matching
- power management
- clocks and regulators handling

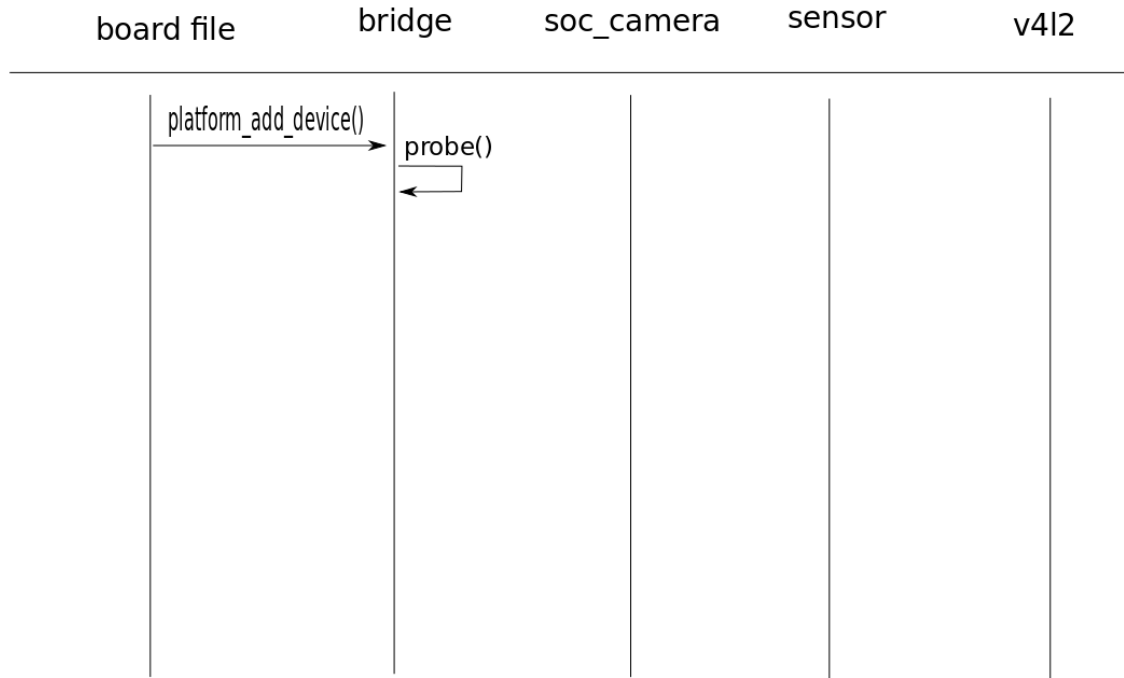
# video4linux2: device probing

- Device matching and probing:
  - The old world: i2c addresses based
  - The new world: firmware based

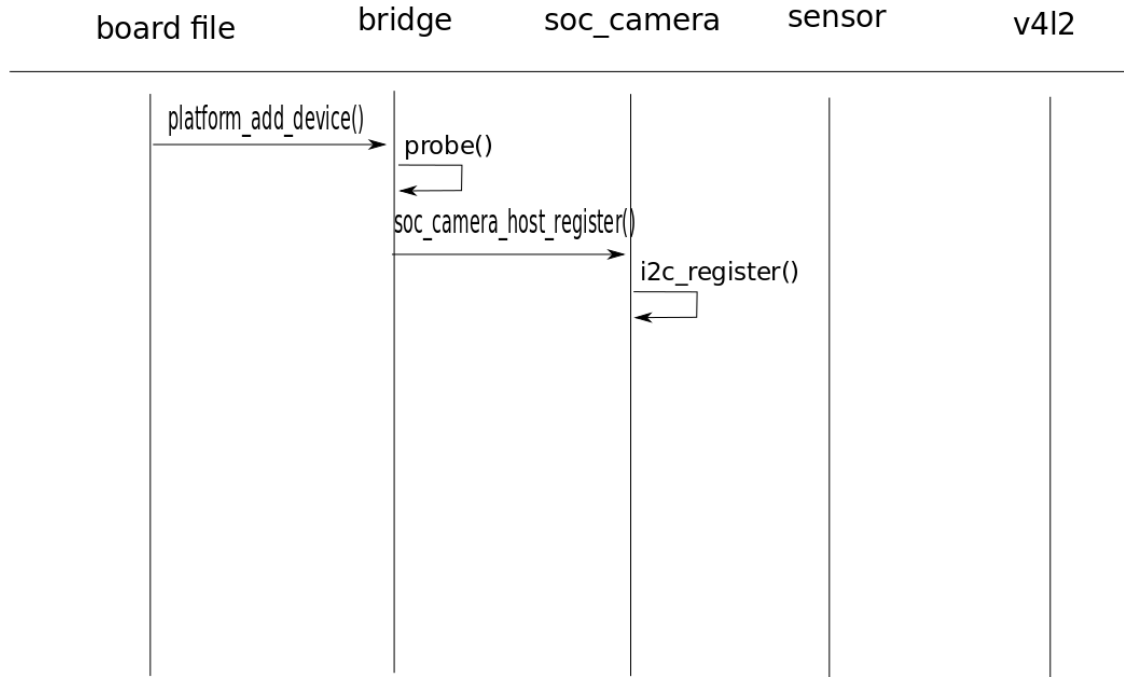
# video4linux2: device probing

board file	bridge	soc_camera	sensor	v4l2

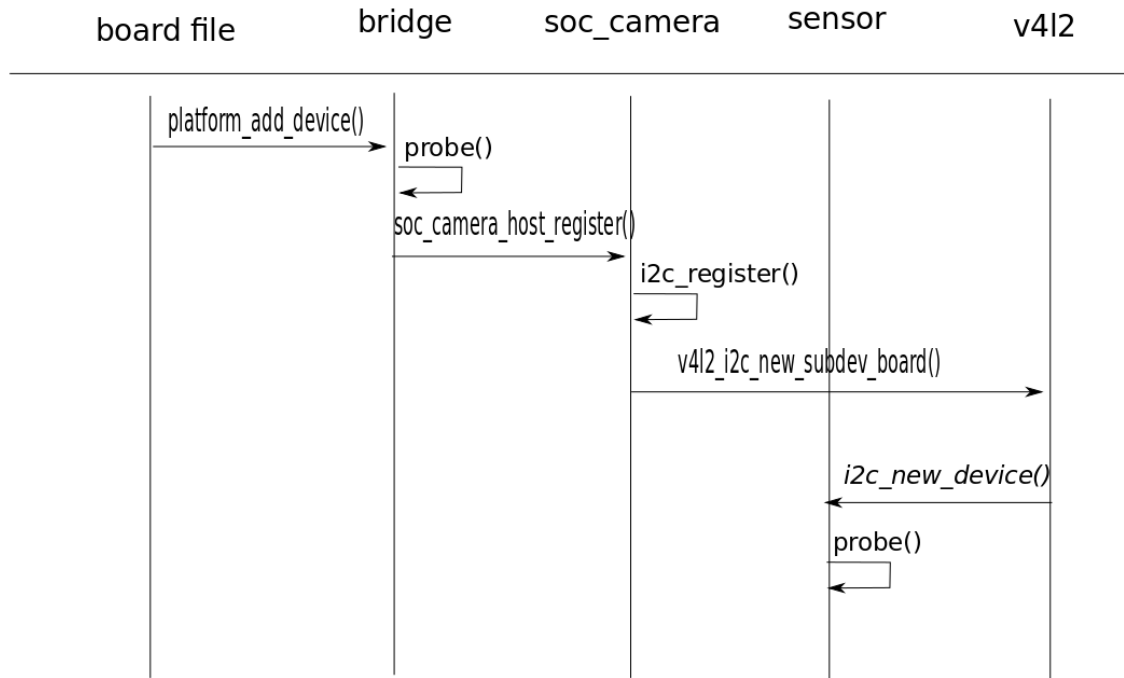
# video4linux2: device probing



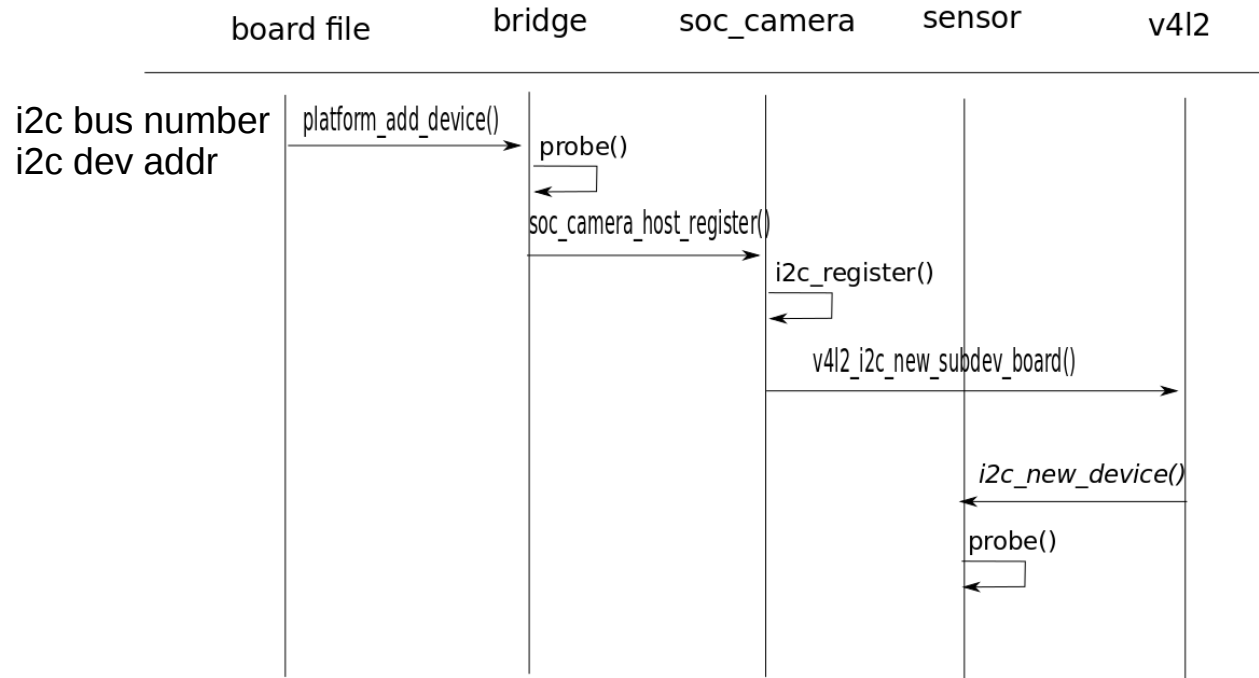
# video4linux2: device probing



# video4linux2: device probing

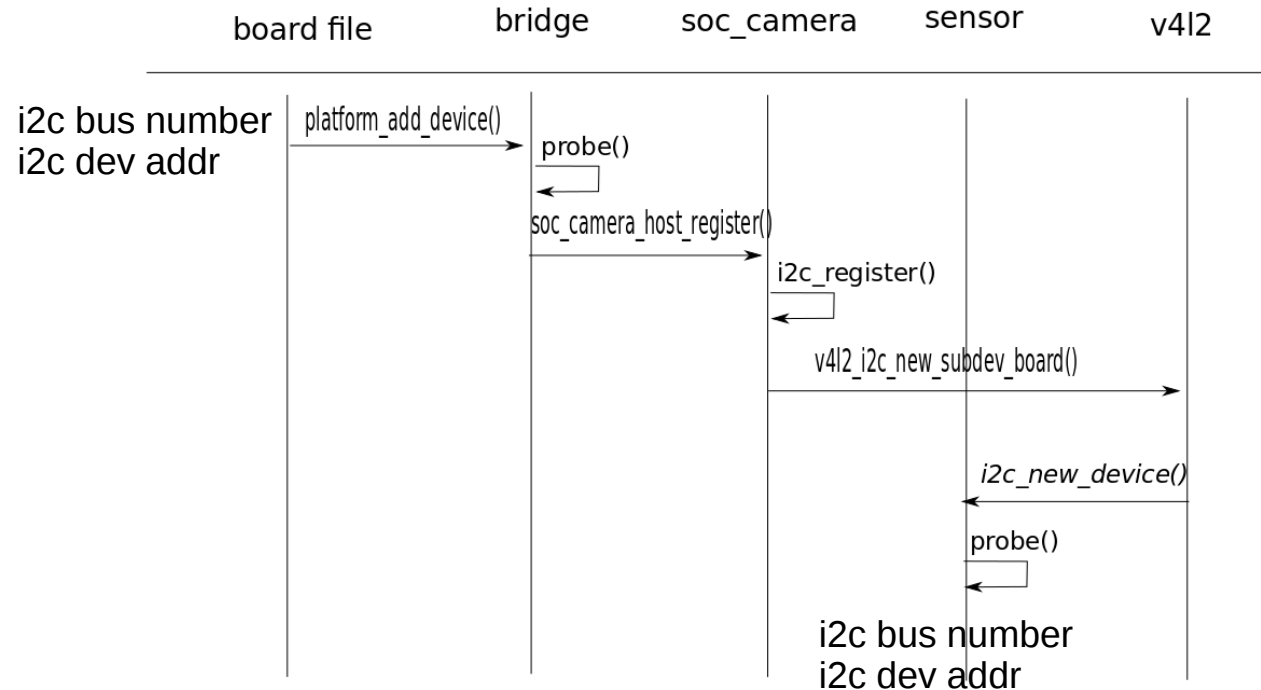


# video4linux2: device probing





# video4linux2: device probing



# video4linux2: device probing

- Old world
  - Device identified by i2c bus number and i2c address
  - Device probing is sequential
  - Guarantees a bridge driver probes before the sensor driver it will connect to

# video4linux2: device probing

- New world
  - Devices are created parsing a firmware description of the system (OF or ACPI)
  - Device are identified by they 'firmware node' references
  - No guarantees on the probing order

# video4linux2: device probing

## DTB

```
soc{
  vin@xxxxxxxx {
    ...
  };

  i2c@xxx {
    ...
    sensor@3a {
      ....
    };
  };
};
```

# video4linux2: device probing

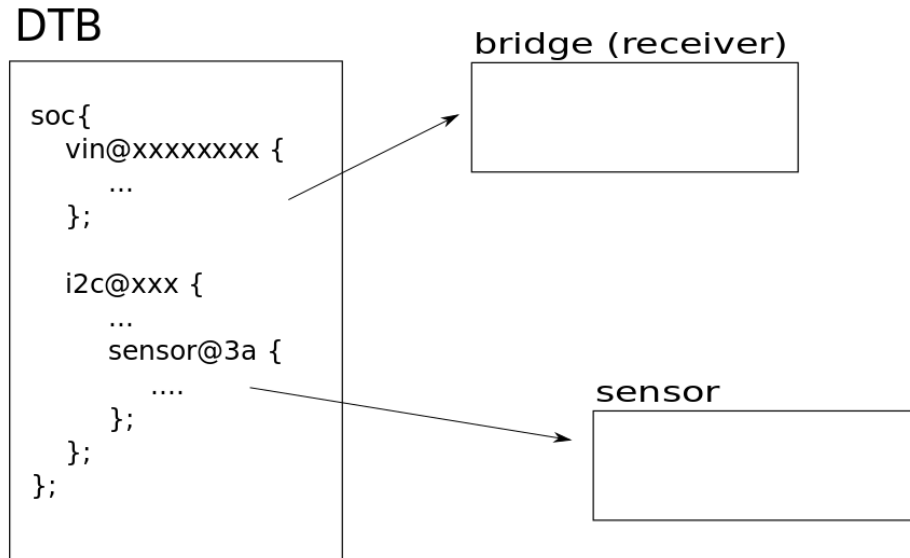
DTB

```
soc{  
  vin@xxxxxxxx {  
    ...  
  };  
  
  i2c@xxx {  
    ...  
    sensor@3a {  
      ....  
    };  
  };  
};
```

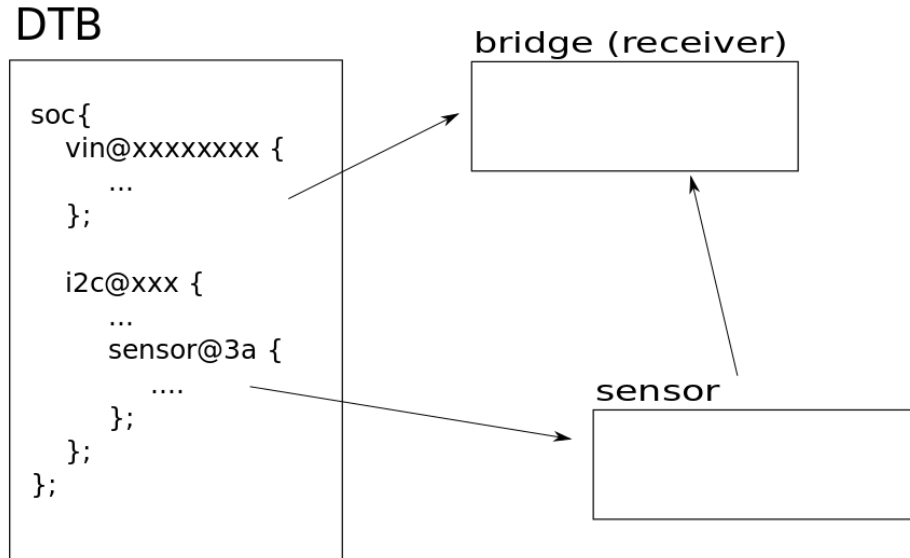
bridge (receiver)



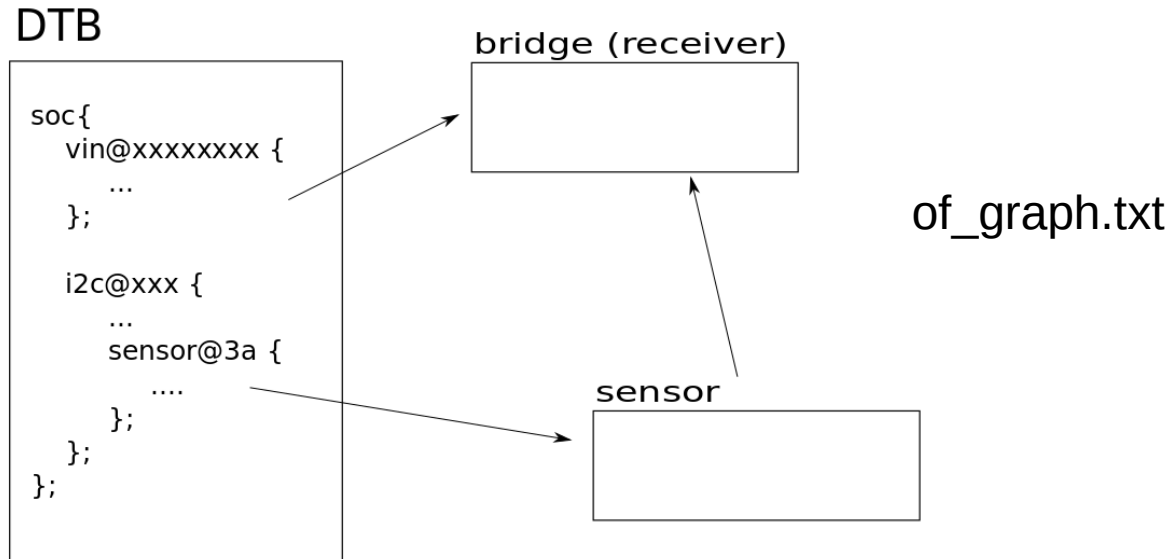
# video4linux2: device probing



# video4linux2: device probing



# video4linux2: device probing





# video4linux2: device probing

DTB

```
soc{  
  vin@xxxxxxxx {  
    ...  
  };  
  
  i2c@xxx {  
    ...  
    sensor@3a {  
      ...  
    };  
  };  
};
```

bridge (receiver)



sensor



of\_graph.txt

ACPI\_DSD extension

# video4linux2: device probing

DTB

```
soc{  
  vin@xxxxxxxx {  
    ...  
  };  
  
  i2c@xxx {  
    ...  
    sensor@3a {  
      ...  
    };  
  };  
};
```

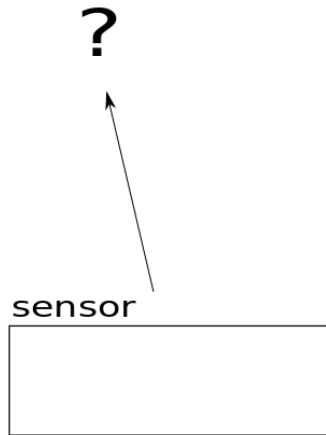
sensor



# video4linux2: device probing

DTB

```
soc{  
  vin@xxxxxxxx {  
    ...  
  };  
  
  i2c@xxx {  
    ...  
    sensor@3a {  
      ...  
    };  
  };  
};
```



# video4linux2: device probing

- Device probing is now *asynchronous*
- Devices are now identified by their firmware node references

# video4linux2: device probing

- Device probing is now *asynchronous*
- Devices are now identified by their firmware node references
- V4L2 framework support
  - *v4l2-async*
  - *v4l2-fwnode*

# video4linux2: device probing

Bridge (receiver)

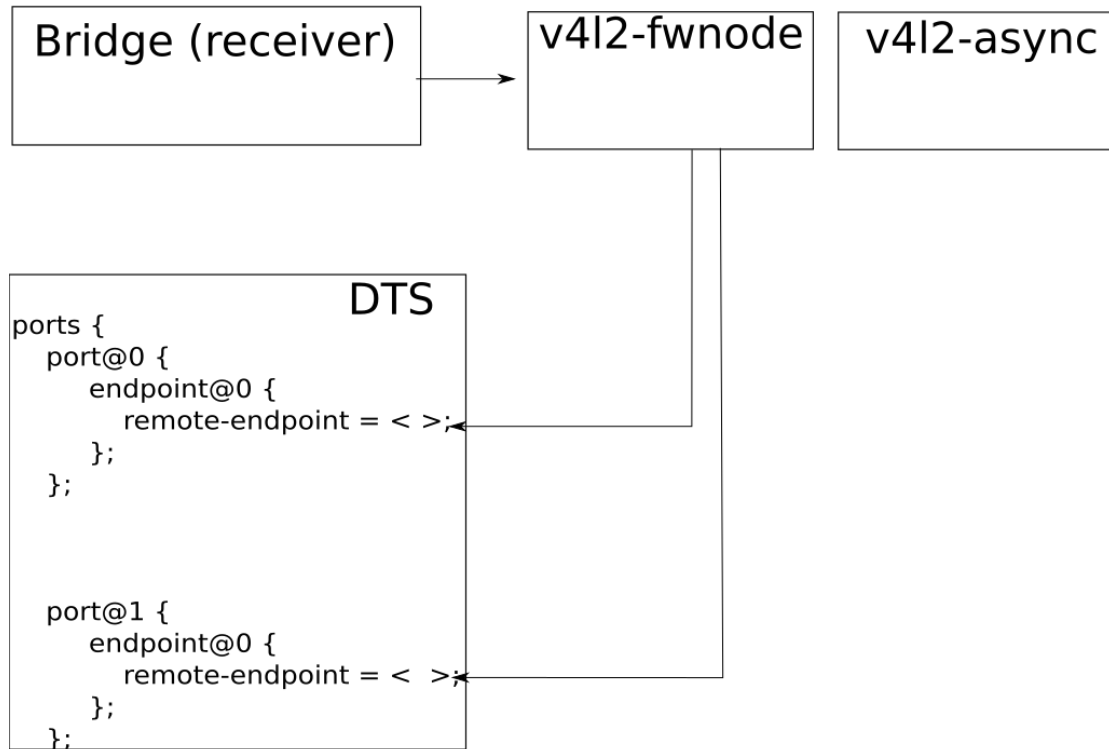
v4l2-fwnode

v4l2-async

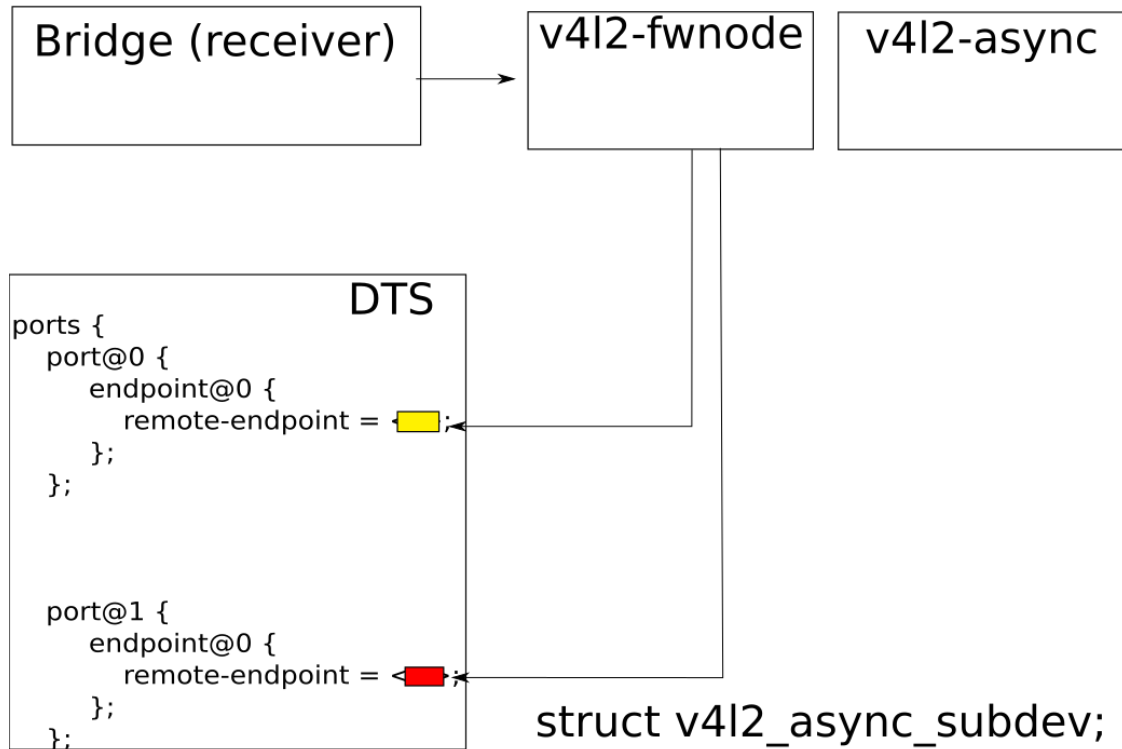
DTS

```
ports {  
    port@0 {  
        endpoint@0 {  
            remote-endpoint = < >;  
        };  
    };  
  
    port@1 {  
        endpoint@0 {  
            remote-endpoint = < >;  
        };  
    };  
};
```

# video4linux2: device probing



# video4linux2: device probing





# video4linux2: device probing

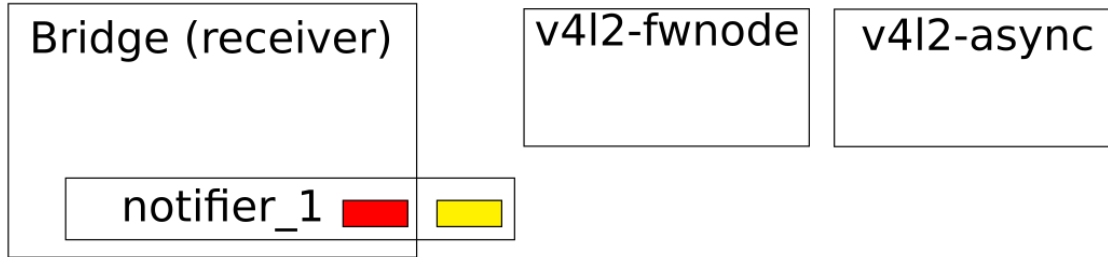
Bridge (receiver)



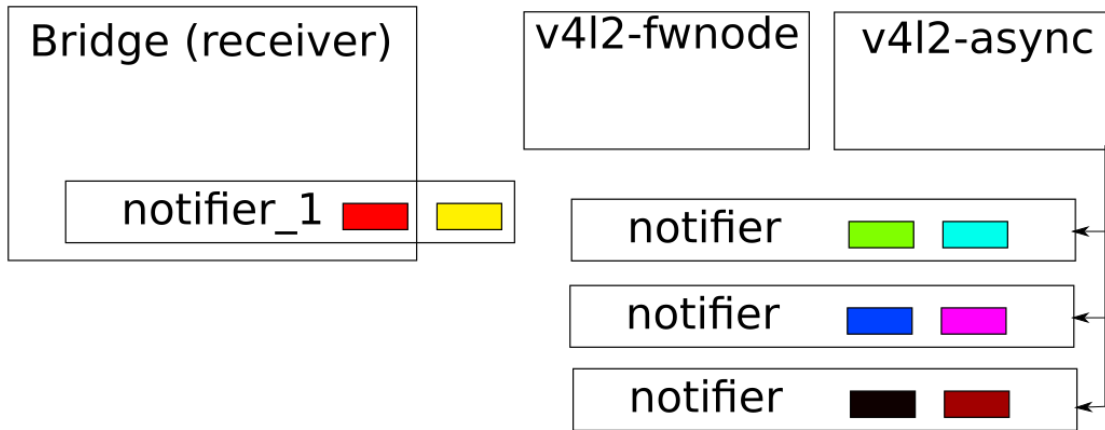
v4l2-fwnode

v4l2-async

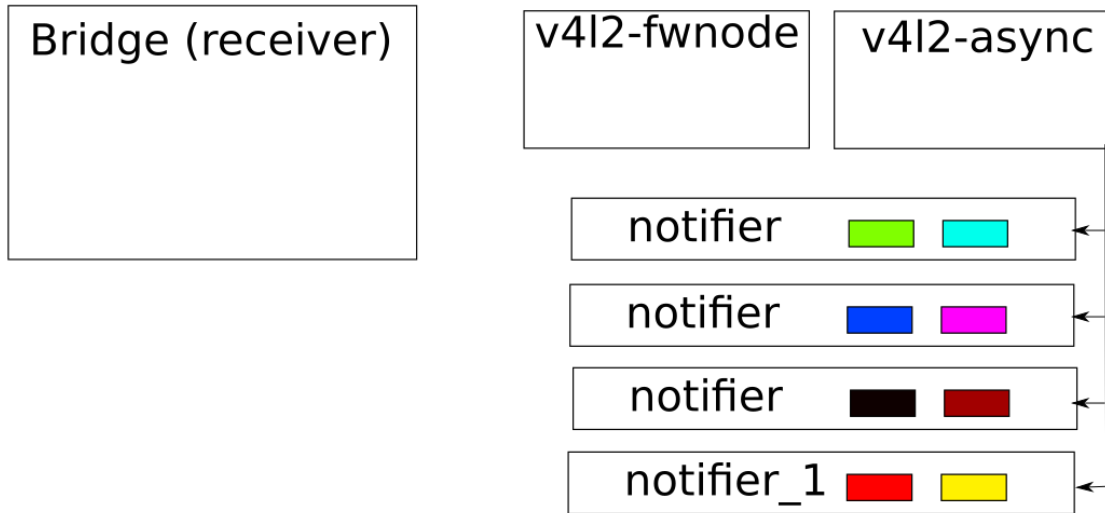
# video4linux2: device probing



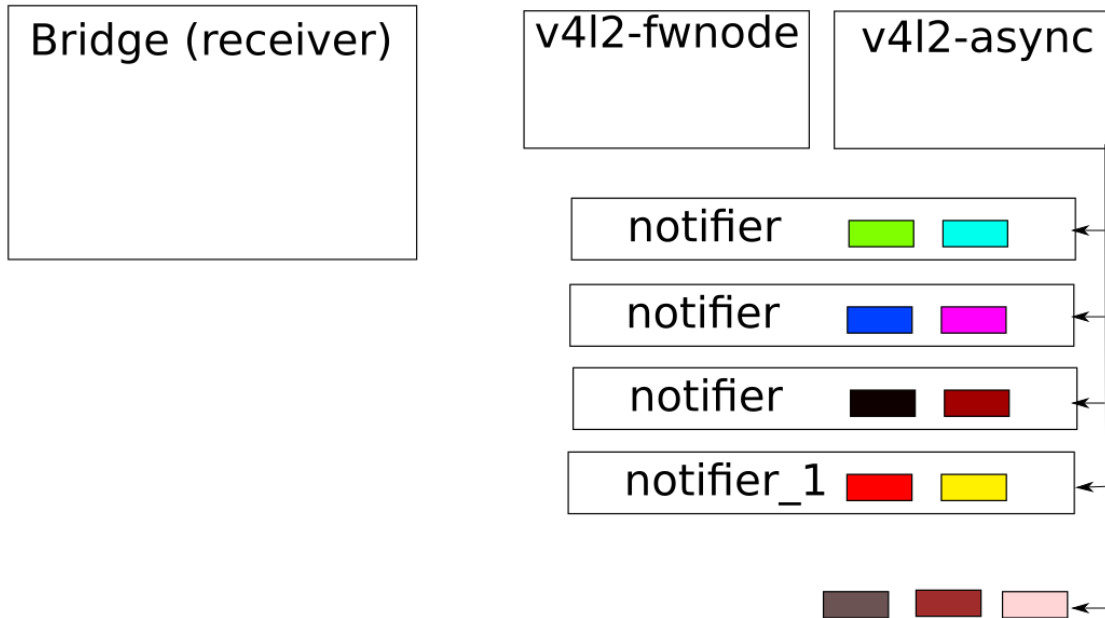
# video4linux2: device probing



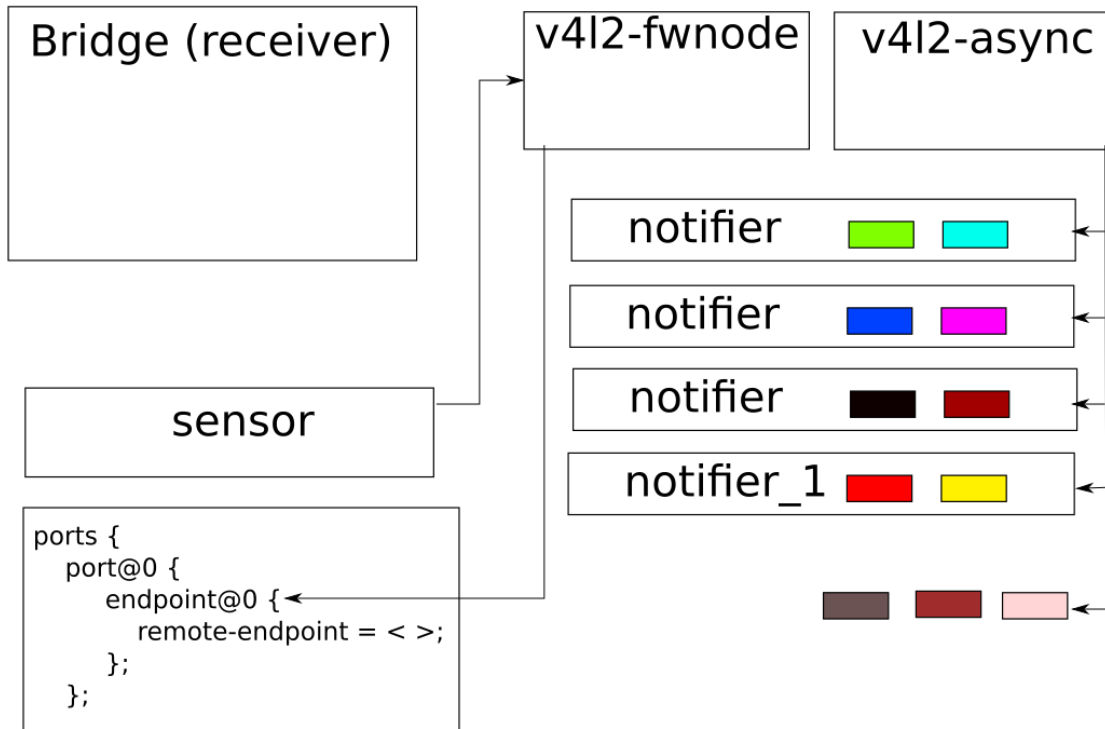
# video4linux2: device probing



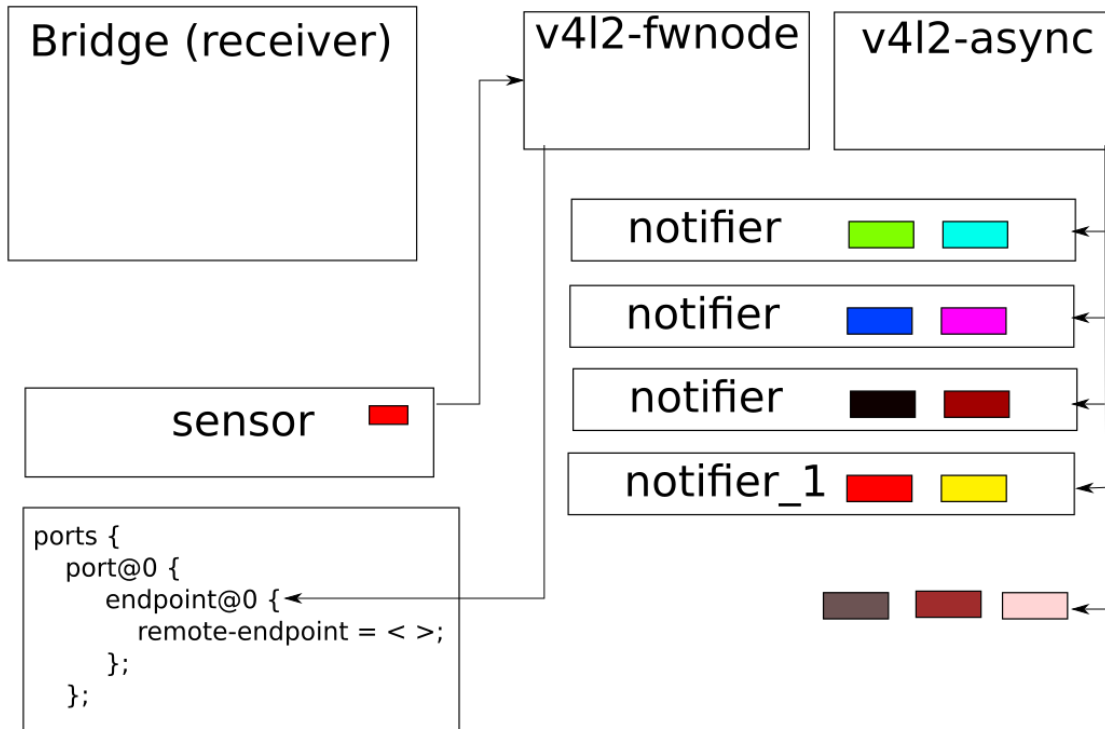
# video4linux2: device probing



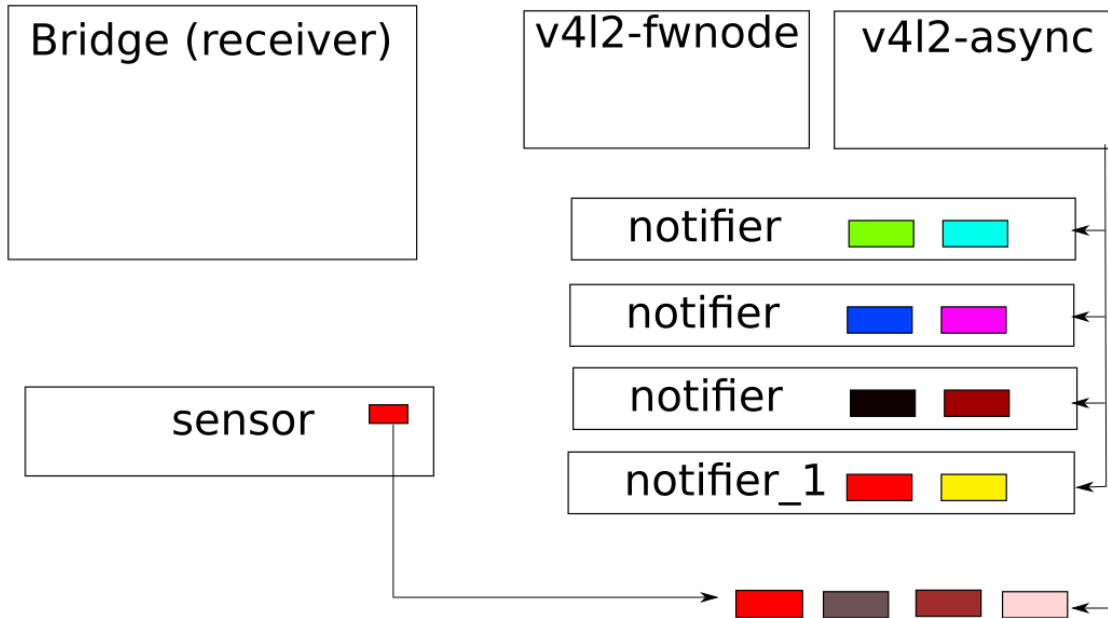
# video4linux2: device probing



# video4linux2: device probing

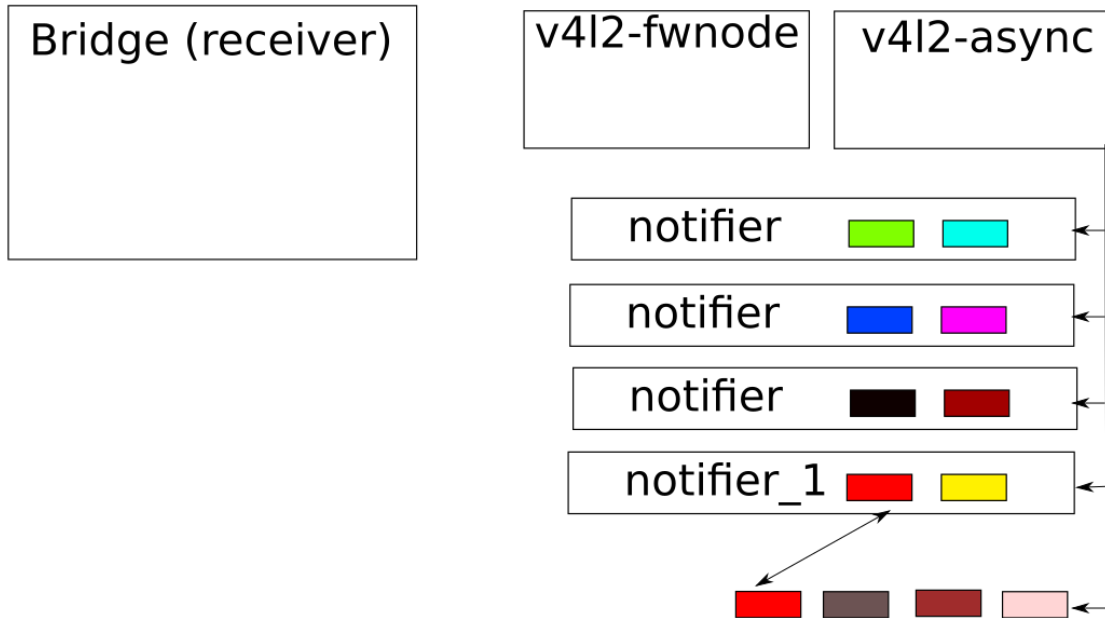


# video4linux2: device probing

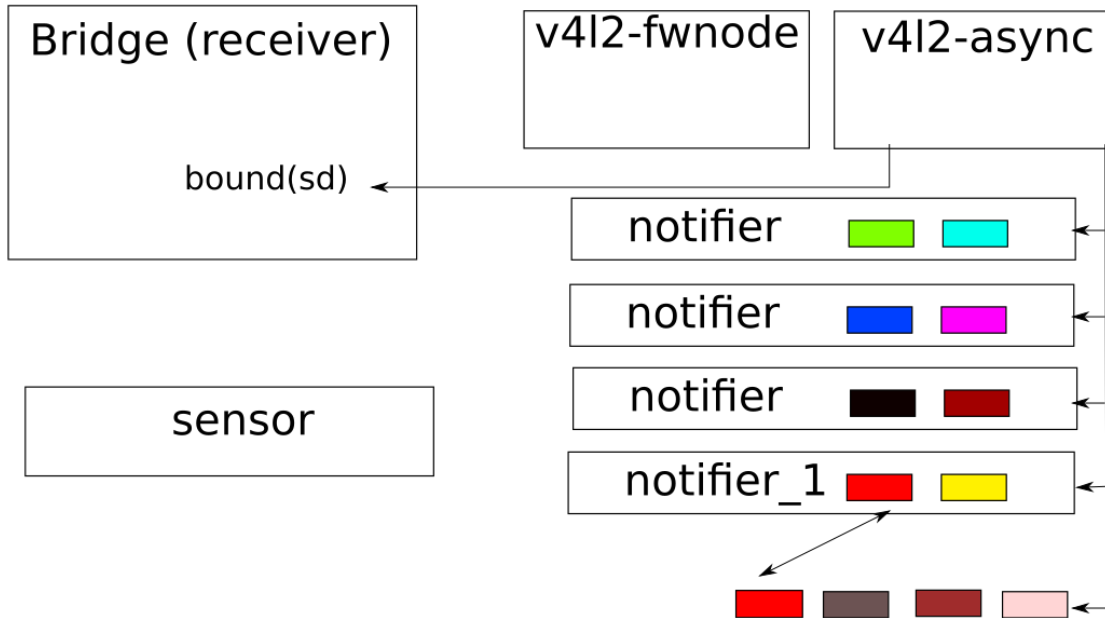




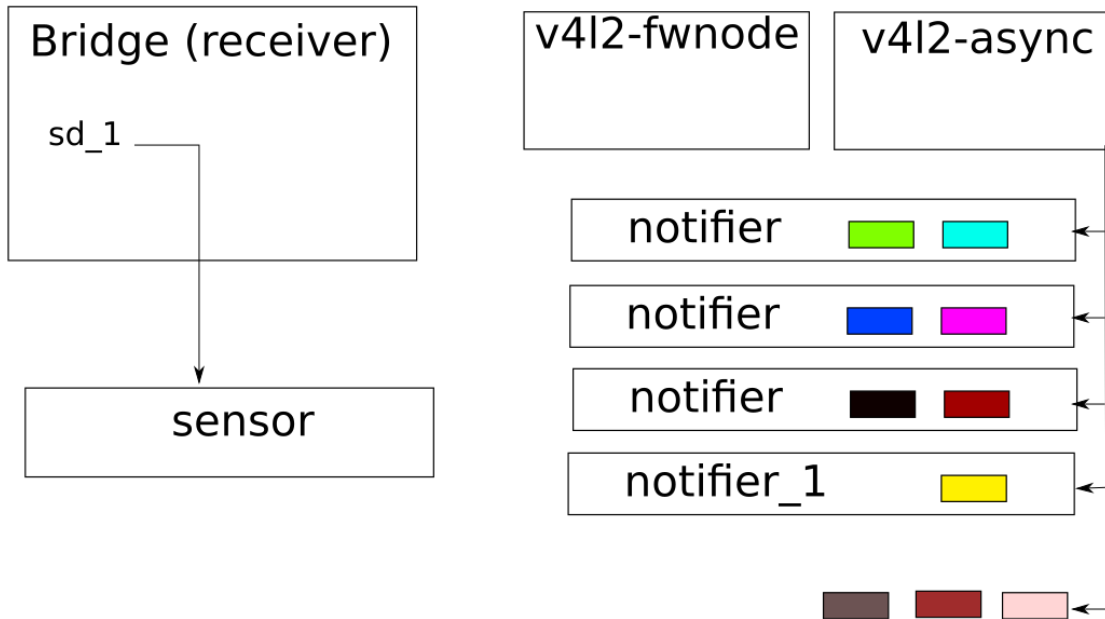
# video4linux2: device probing



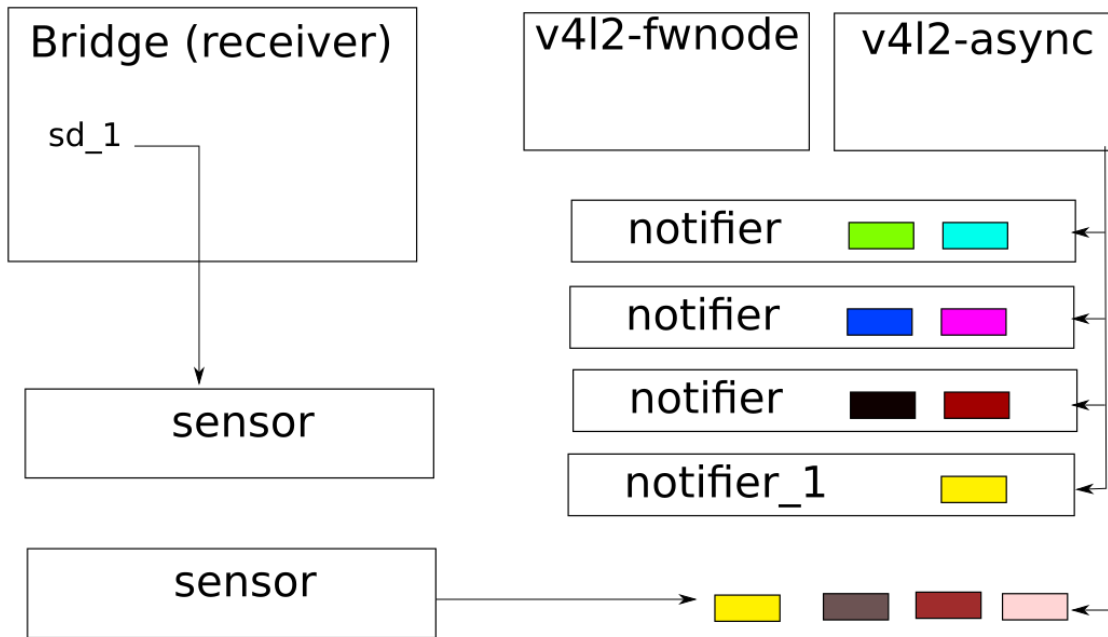
# video4linux2: device probing



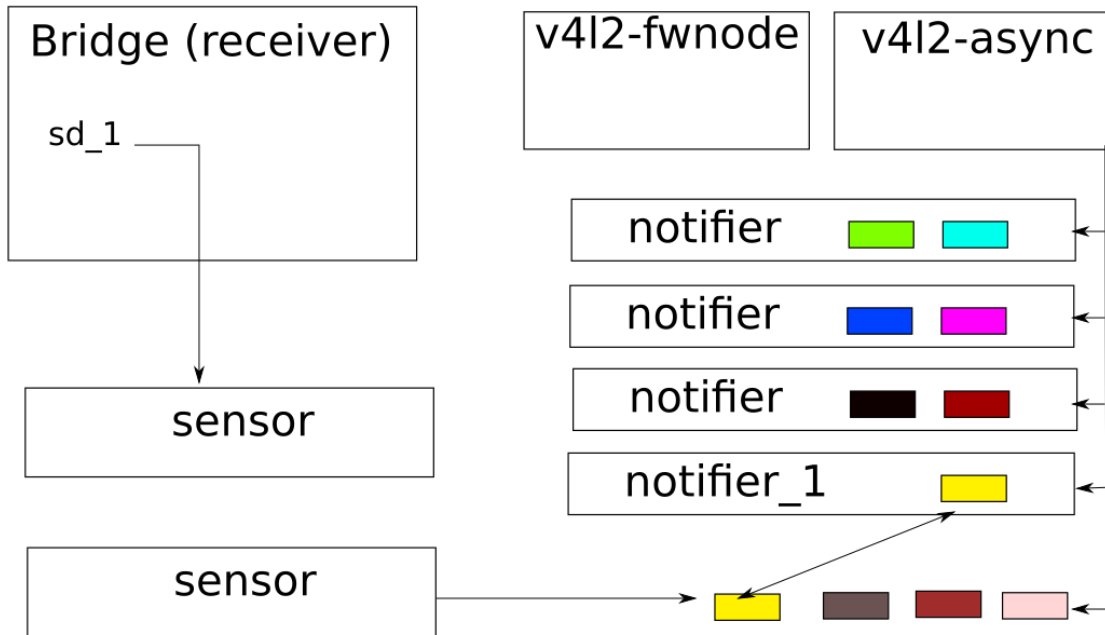
# video4linux2: device probing



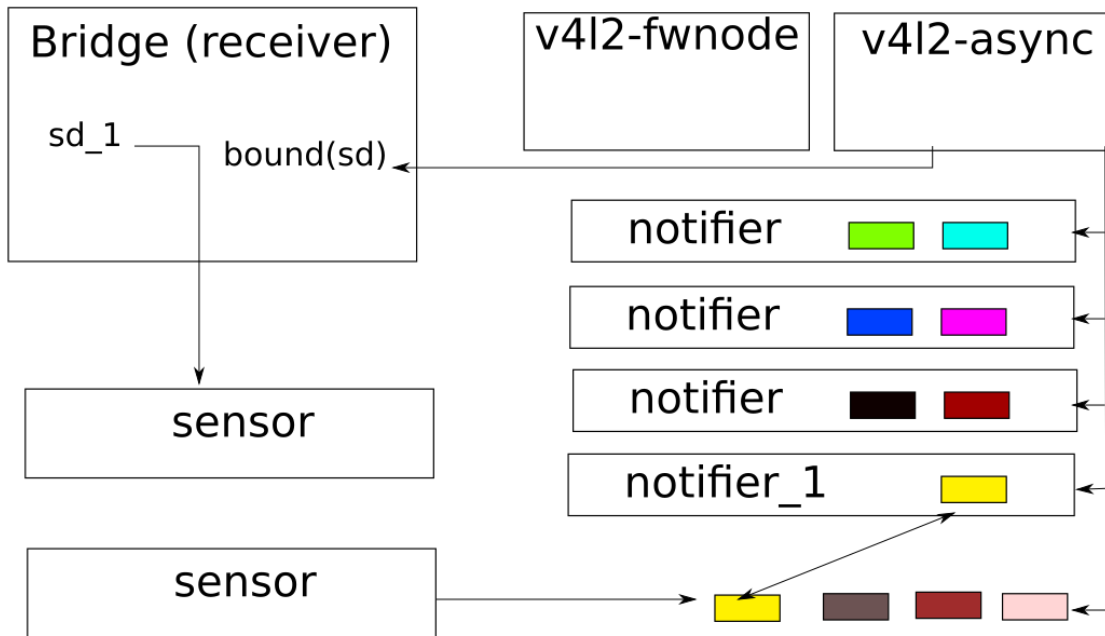
# video4linux2: device probing



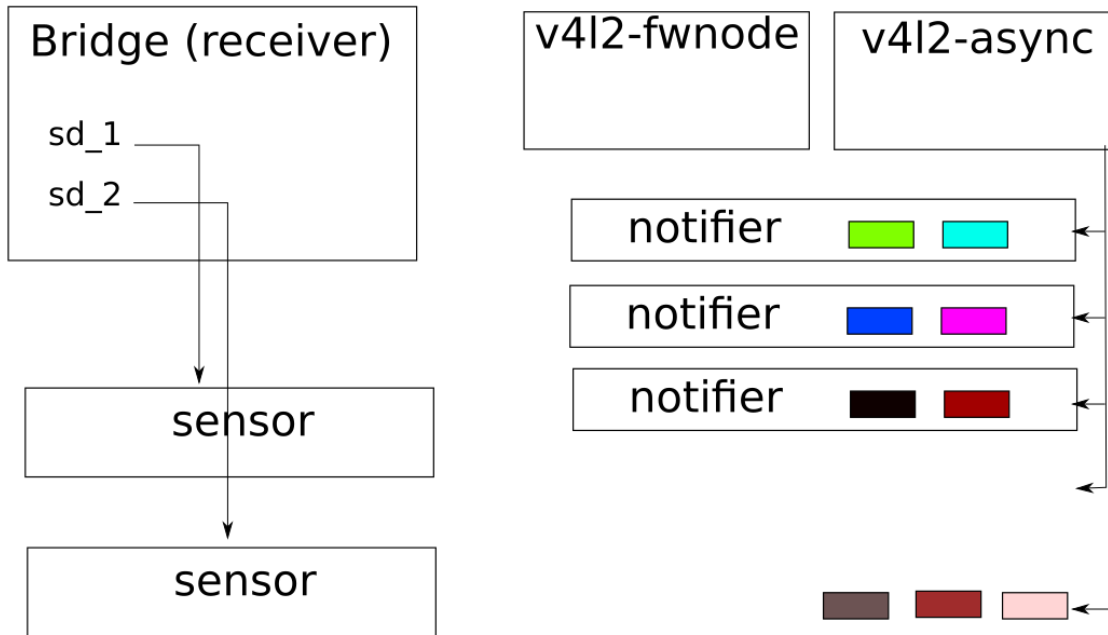
# video4linux2: device probing



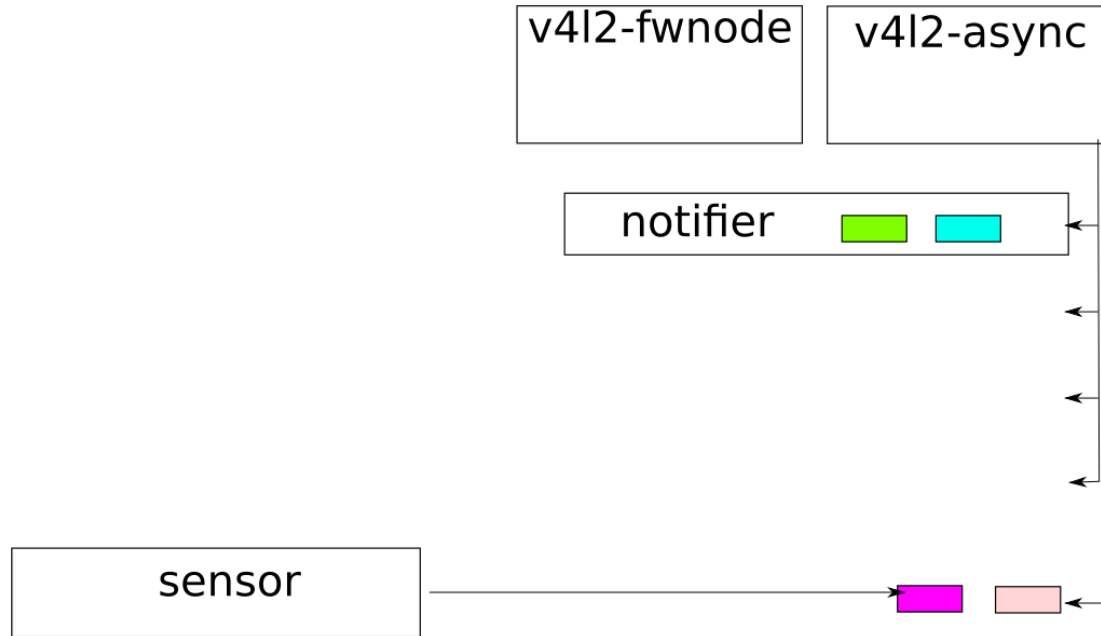
# video4linux2: device probing



# video4linux2: device probing

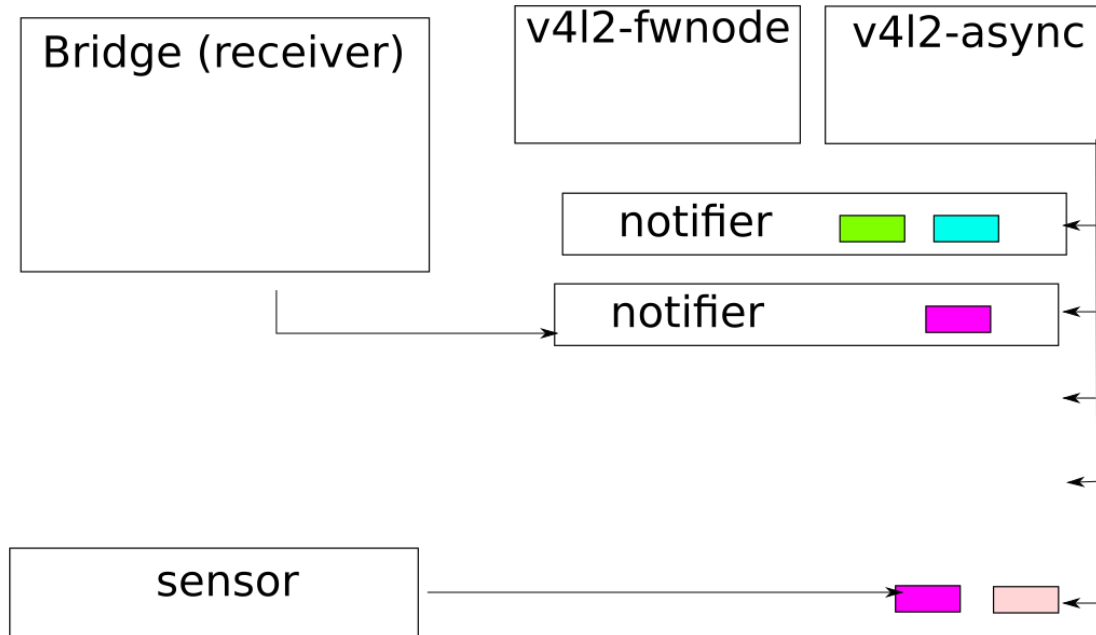


# video4linux2: device probing

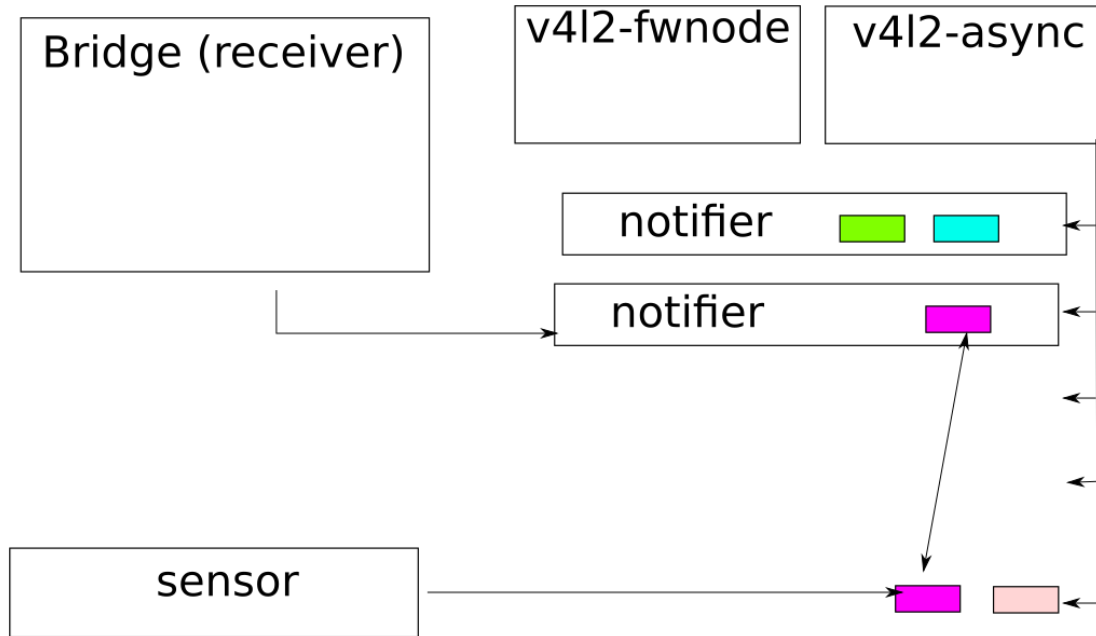




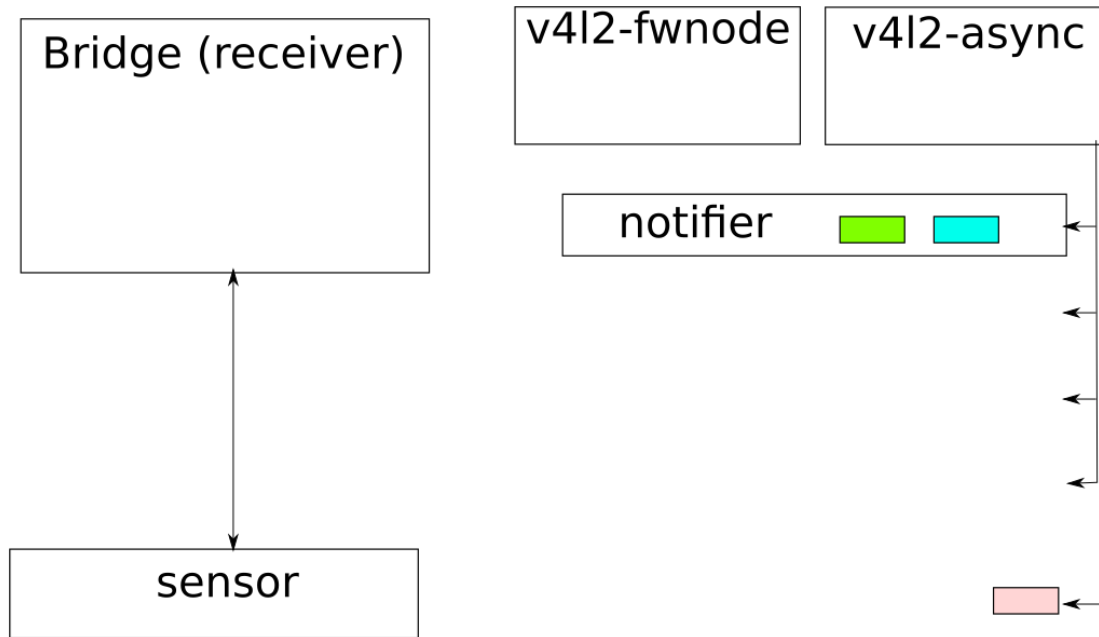
# video4linux2: device probing



# video4linux2: device probing



# video4linux2: device probing



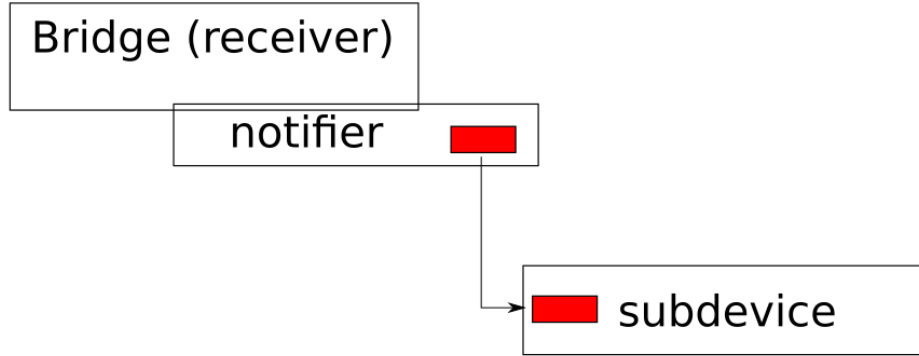
# video4linux2: device probing

- soc\_camera can do that
  - Uses v4l2-async
  - Uses v4l2-fwnode
- What has changed then?

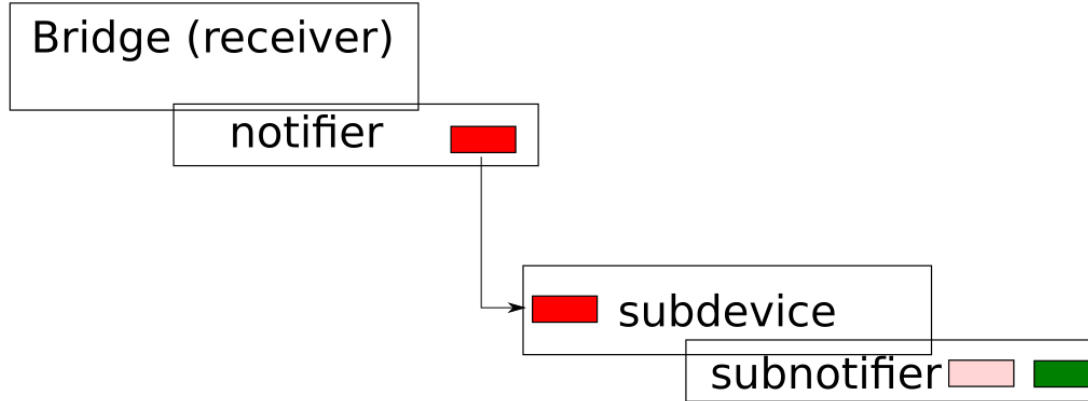
# video4linux2: device probing

- soc\_camera can do that
  - Uses v4l2-async
  - Uses v4l2-fwnode
- What has changed then?
  - That now subdevs can have notifiers too!
  - Introducing subnotifiers (late 2017)  
Niklas, Sakari Laurent – rcar-csi.c

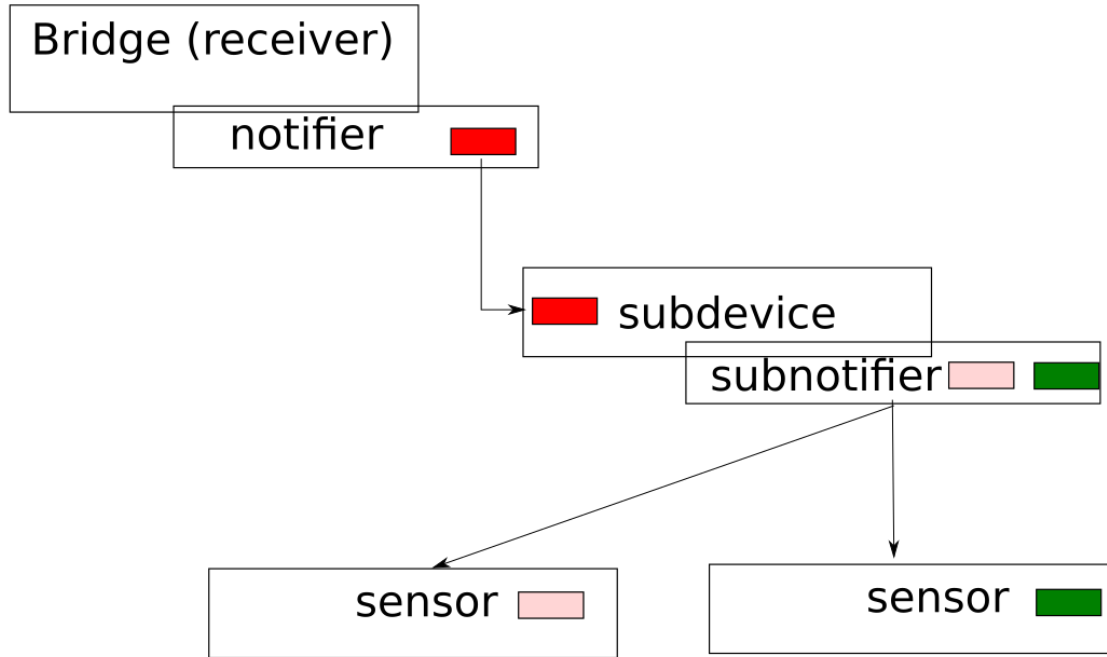
# video4linux2: device probing



# video4linux2: device probing



# video4linux2: device probing





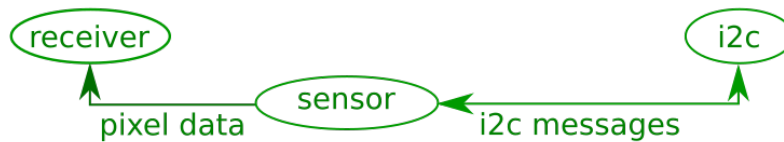
# video4linux2: power management

- Non media controller equipped device
  - Single device node abstraction
  - Sequential operations flow

# video4linux2: power management

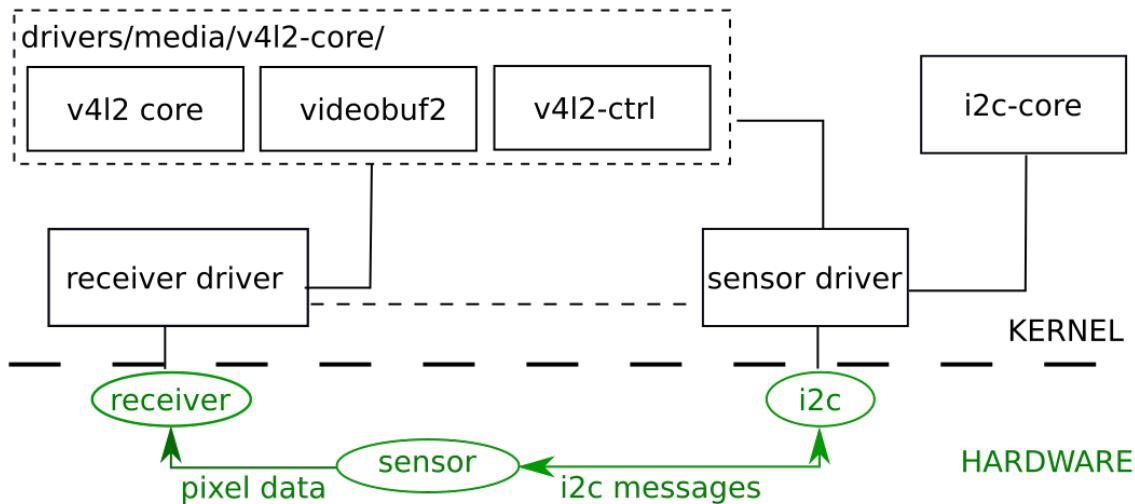
- Non media controller equipped device
  - Single device node abstraction
  - Sequential operations flow
- Media controller equipped device
  - Video device node and subdevice nodes
  - Asynchronous sequence of operations

# video4linux2: power management

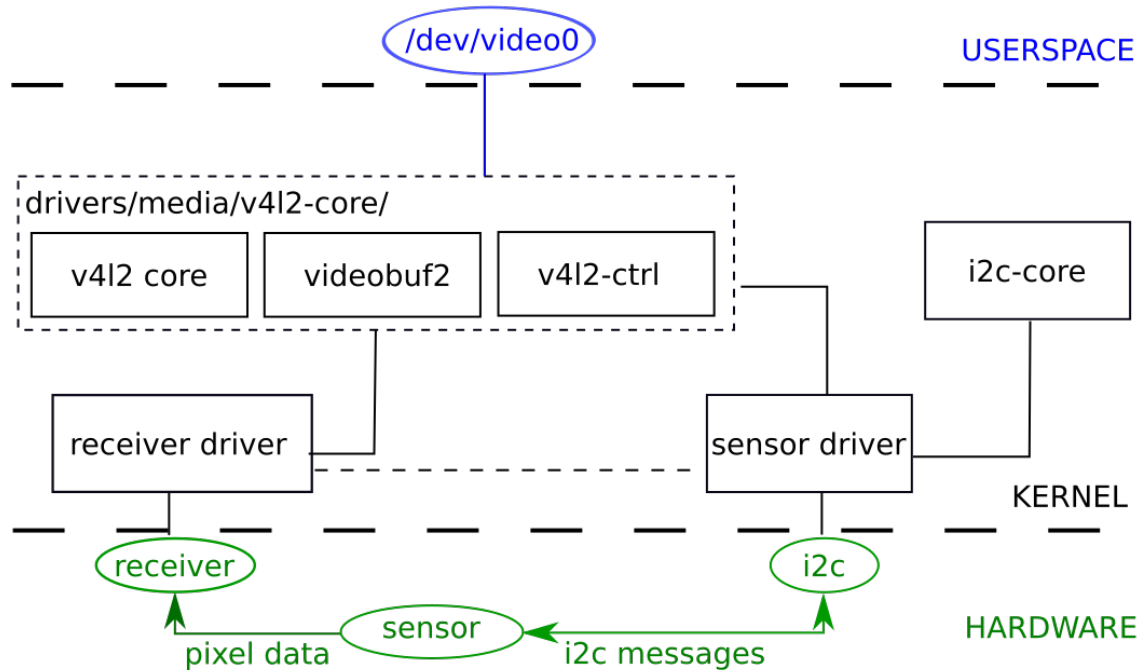


HARDWARE

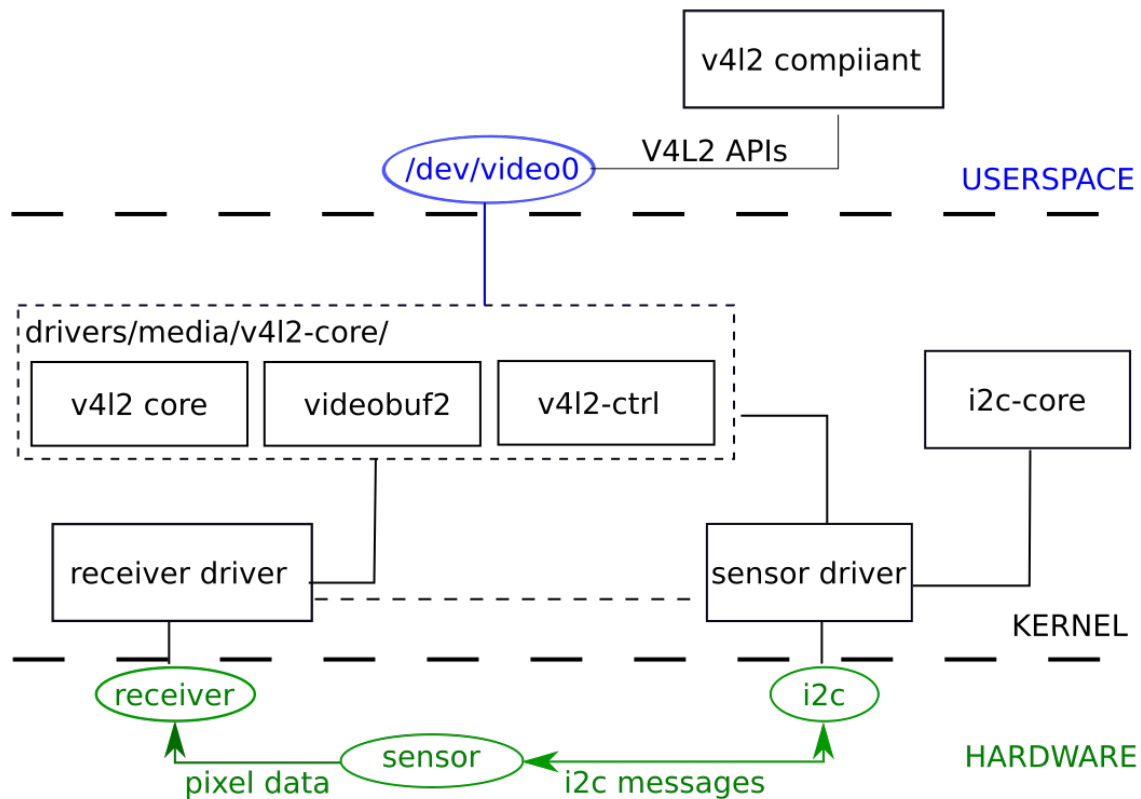
# video4linux2: power management



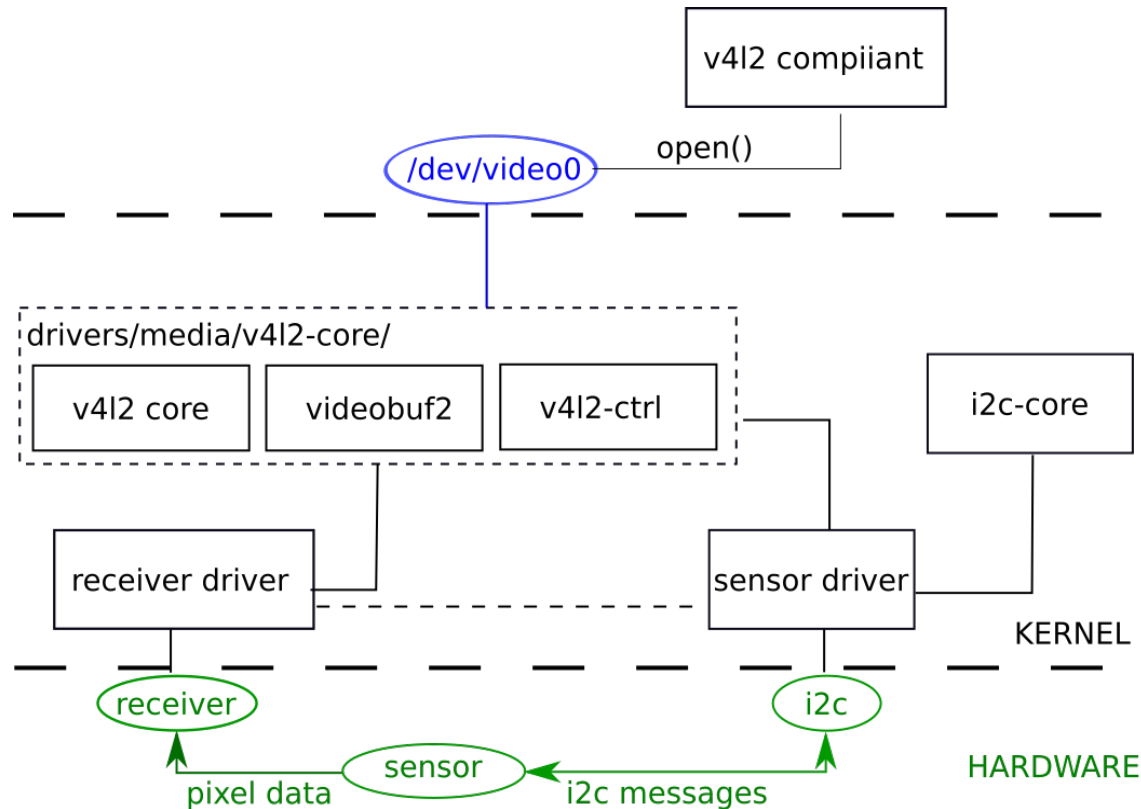
# video4linux2: power management



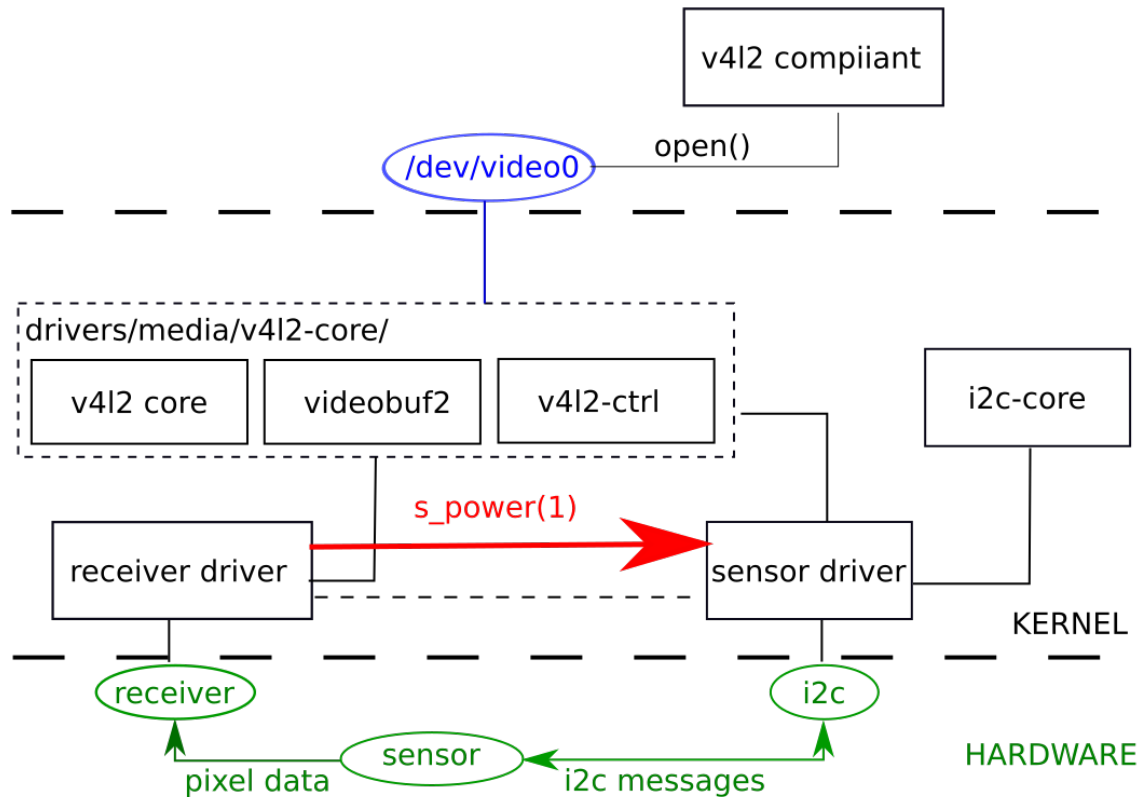
# video4linux2: power management



# video4linux2: power management

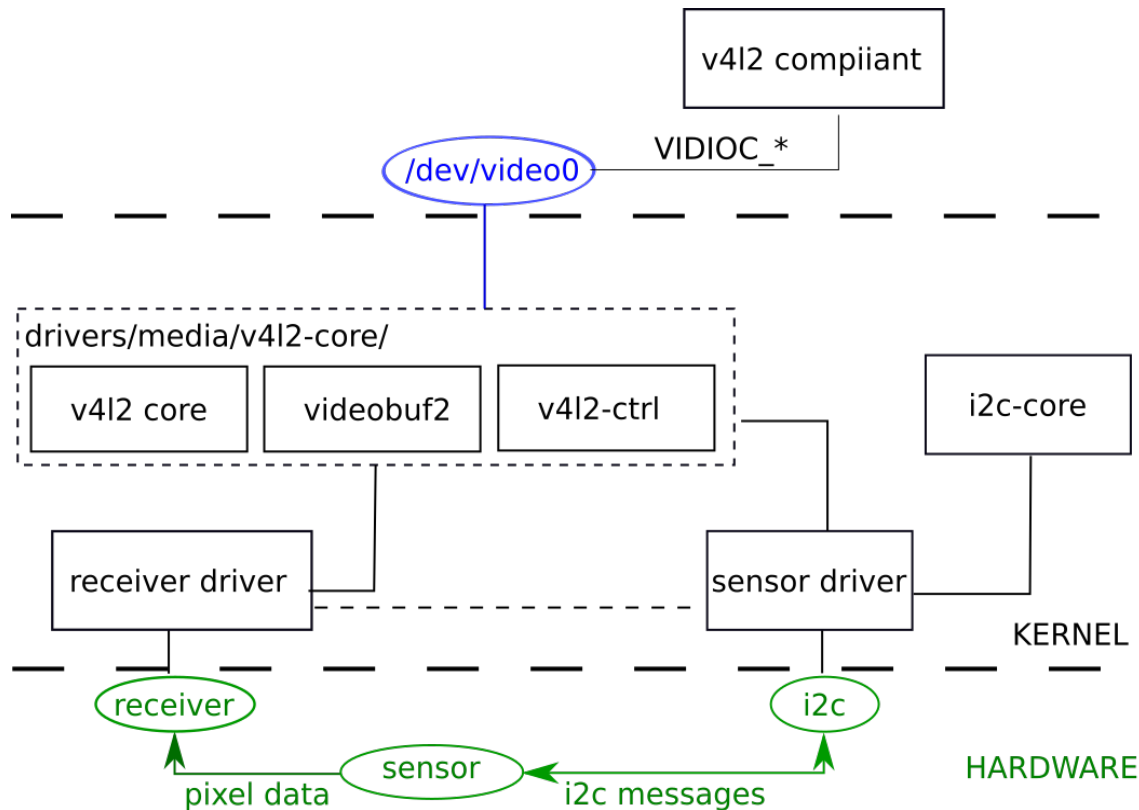


# video4linux2: power management

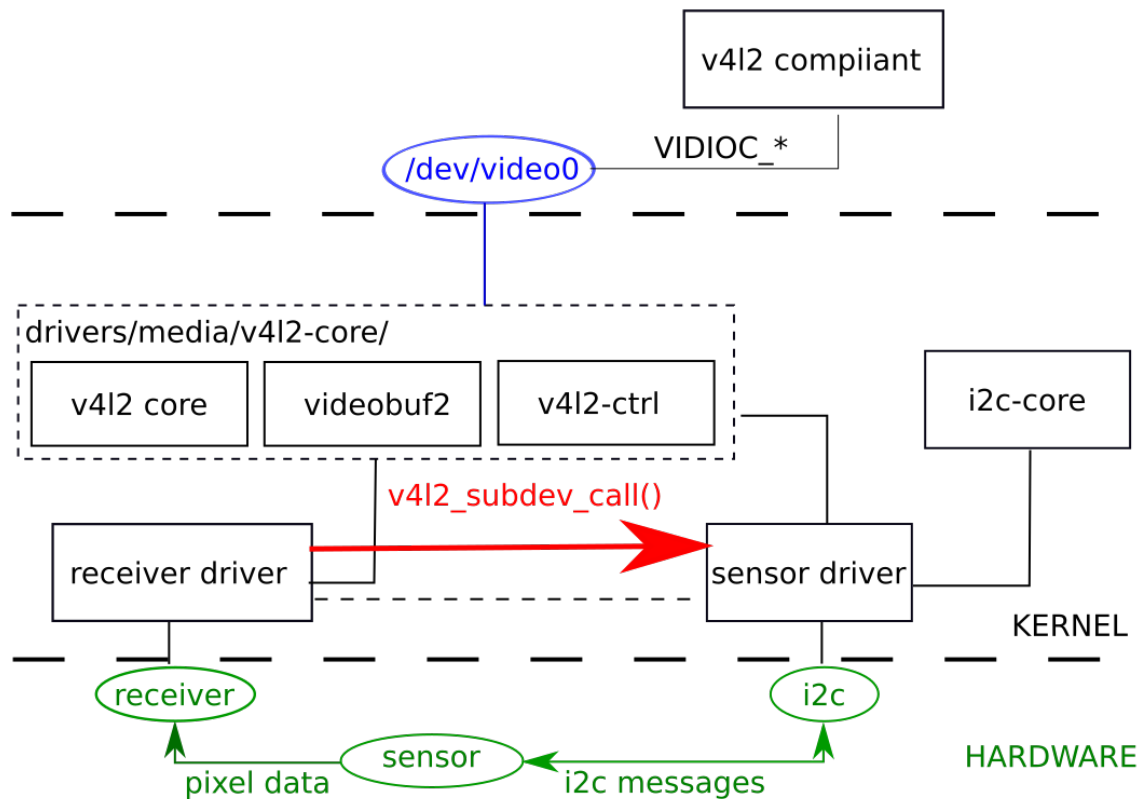




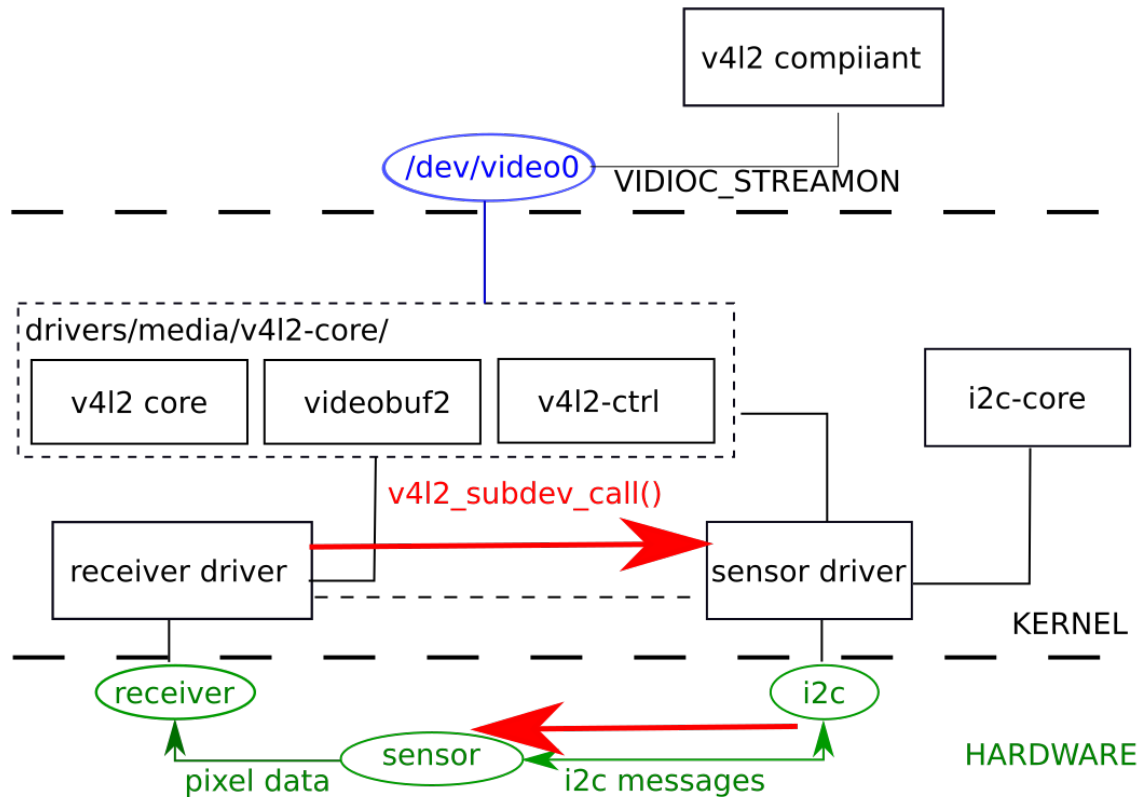
# video4linux2: power management



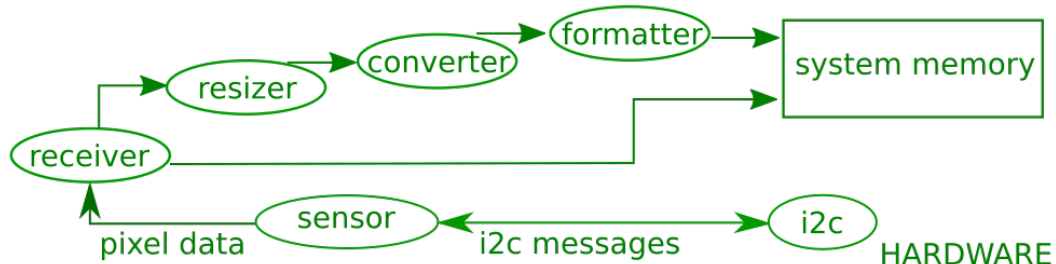
# video4linux2: power management



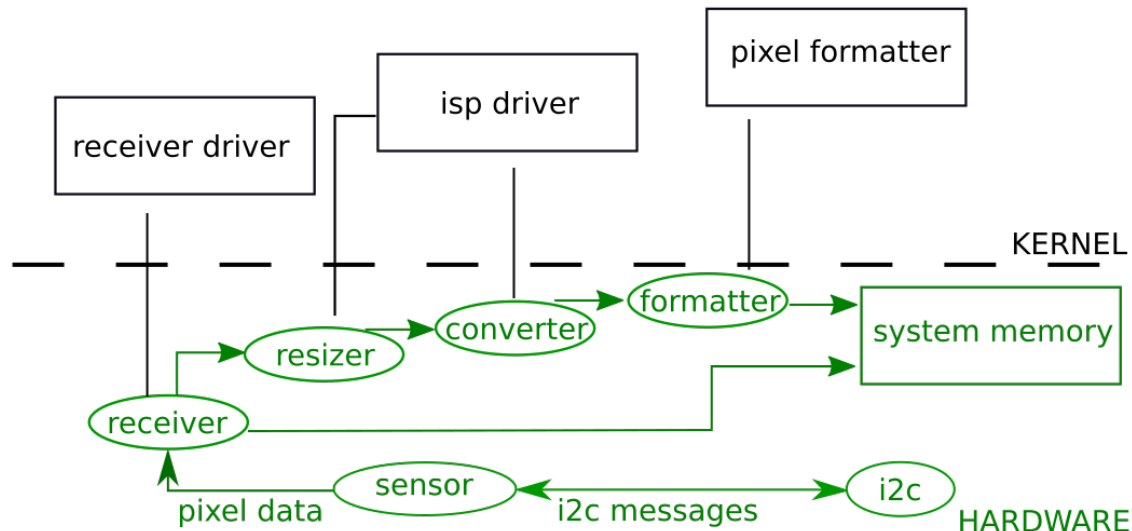
# video4linux2: power management



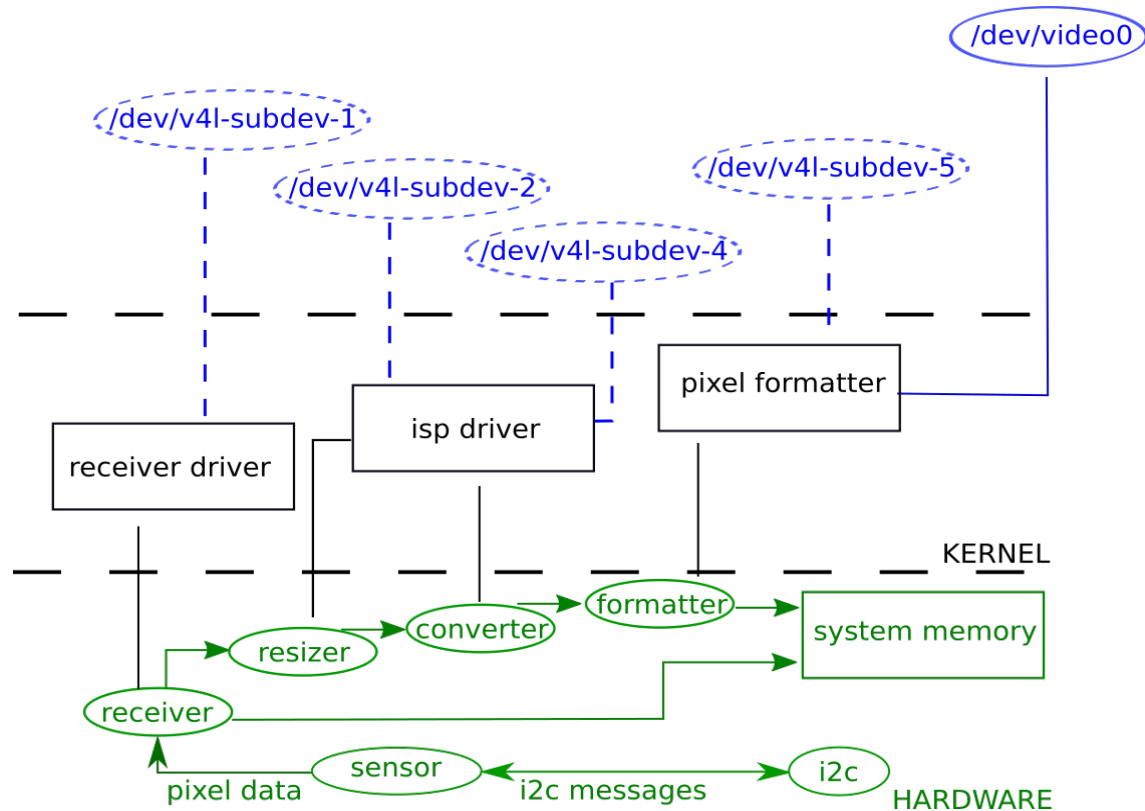
# video4linux2: power management



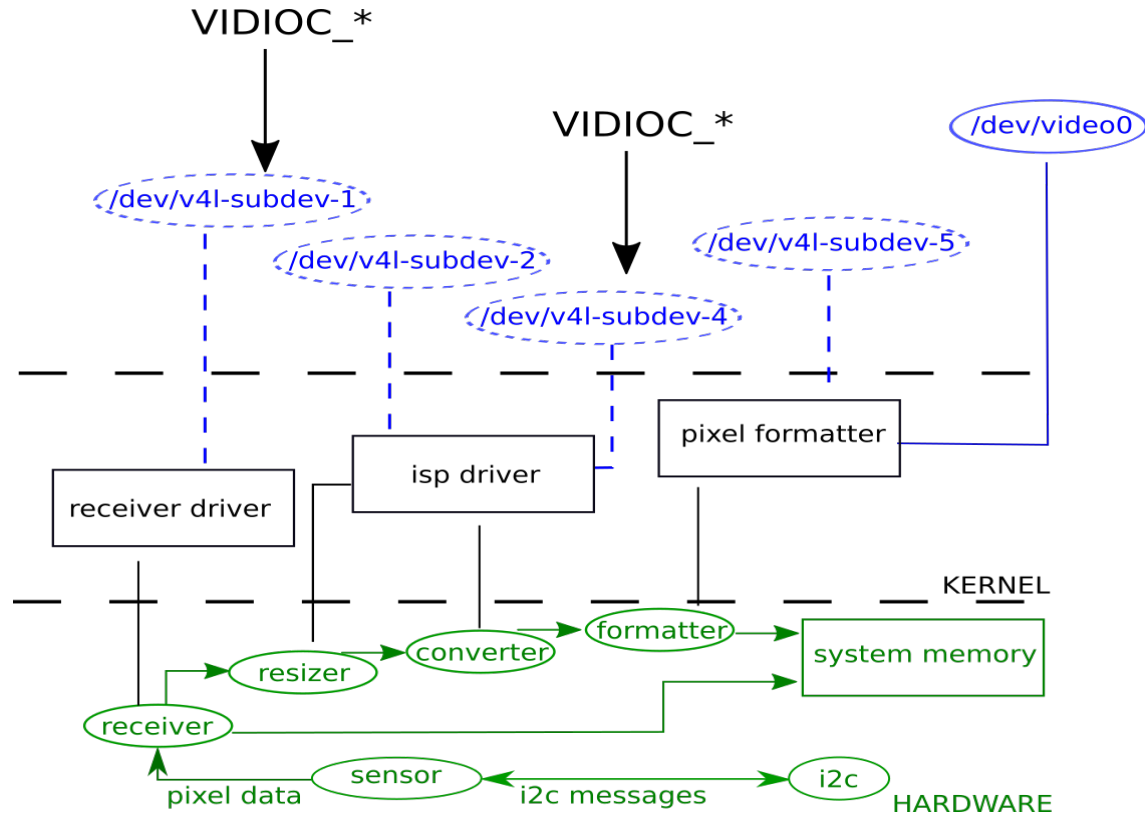
# video4linux2: power management



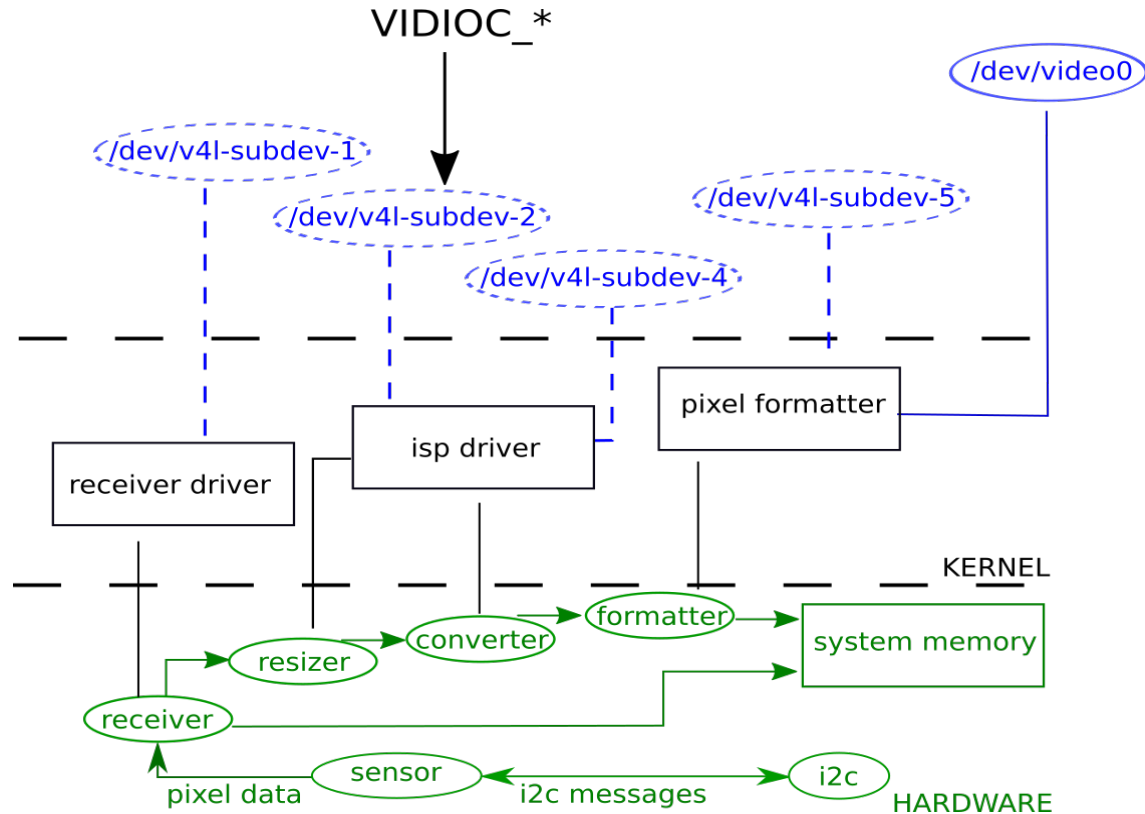
# video4linux2: power management



# video4linux2: power management

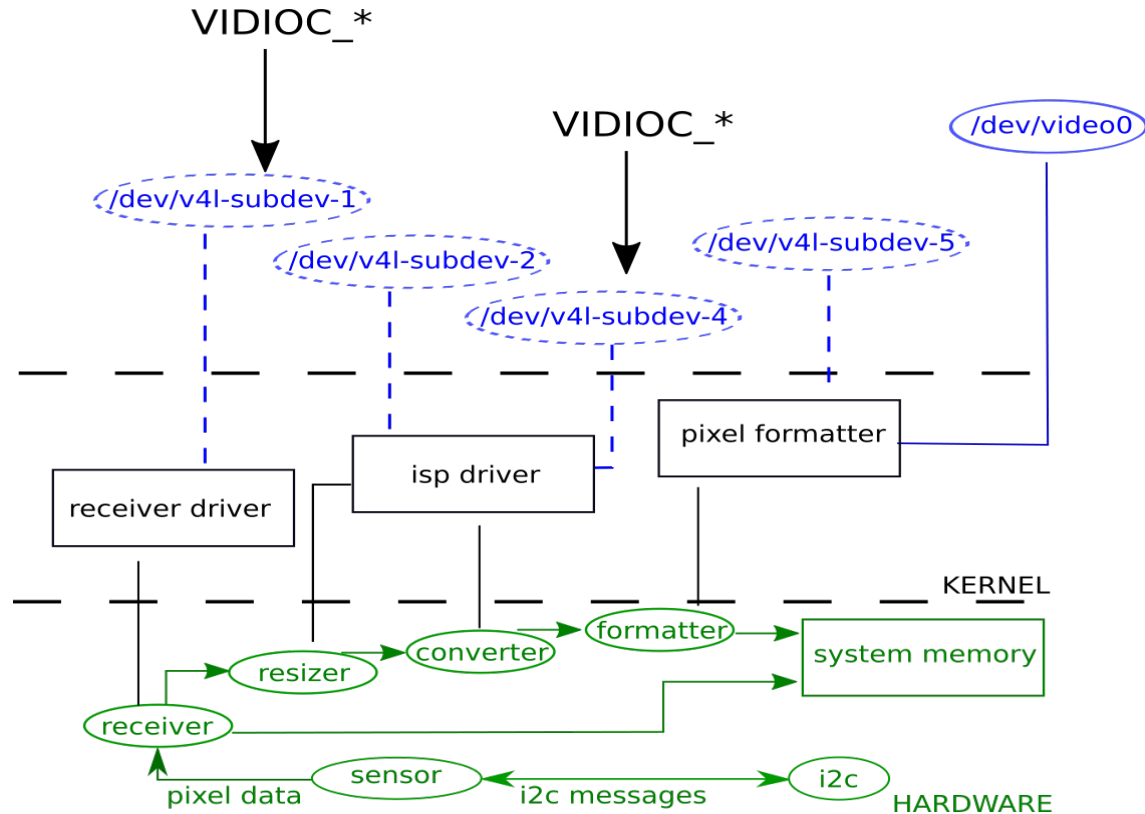


# video4linux2: power management





# video4linux2: power management



# video4linux2: power management

- CACHE

# video4linux2: power management

- CACHE YOUR

# video4linux2: power management

- **CACHE YOUR SETTINGS**

# video4linux2: power management

- CACHE YOUR SETTINGS
- Maintain a driver-wise 'power state' notion

# video4linux2: power management

- CACHE YOUR SETTINGS
- Maintain a *ref-counted* driver-wise ‘power state’ notion
- Apply the cached settings at stream-on time

# video4linux2: power management

- CACHE YOUR SETTINGS
- Maintain a *ref-counted* driver-wise ‘power state’ notion
- Apply the cached settings at stream-on time
- Use RUNTIME\_PM whenever possible

# video4linux2: clks, gpios, regulators

- Legacy board files provided to drivers  
power management routines

```
static struct soc_camera_link ov7725_link = {  
    .power          = ov7725_power,  
    .board_info     = &migor_i2c_camera[0],  
    .i2c_adapter_id = 0,  
    .priv           = &ov7725_info,  
};
```



# video4linux2: clks, gpios, regulators

- Use gpio, clock, and regulator frameworks
- Collect references from firmware
  - `*_get(dev, "name");`
- Have the driver enable/disable them at s\_power time

# Practical: ov772x.c

- Copy the driver code from *soc\_camera*

```
media: i2c: Copy ov772x soc_camera sensor driver
```

Copy the *soc\_camera* based driver in *v4l2* sensor driver directory.  
This commit just copies the original file without modifying it.

No modification to *KConfig* and *Makefile* as *soc\_camera* framework dependencies need to be removed first in next commit.

```
drivers/media/i2c/ov772x.c | 1124 ++++++++++++++++++++++++++++++++++++++
+++++++++++++++++++++++++++++++++++++++++++++++++++++++++++++++++++++
+++++++++++++++++++++++++++++++++++++
1 file changed, 1124 insertions(+)
```

# Practical: ov772x.c

- Remove soc\_camera dependencies

media: i2c: ov772x: Remove soc\_camera dependencies

Remove soc\_camera framework dependencies from ov772x sensor driver.

- Handle clock and gpios
- Register async subdevice
- Remove soc\_camera specific g/s\_mbus\_config operations
- Change image format colorspace from JPEG to SRGB as the two use the same colorspace information but JPEG makes assumptions on color components quantization that do not apply to the sensor
- Remove sizes crop from get\_selection as driver can't scale
- Add kernel doc to driver interface header file
- Adjust build system

# Practical: ov772x.c

- Here is where the fun begins:

```
$ git log --oneline drivers/media/i2c/ov772x.c
```

```
3508949 media: i2c: ov772x: Support frame interval handling
4b610d6 media: ov772x: add media controller support
c2cae89 media: ov772x: support device tree probing
34af7d9 media: ov772x: handle nested s_power() calls
95f5a45 media: ov772x: avoid accessing registers under power saving mode
7b9998c media: ov772x: make set_fmt() and s_frame_interval() return -EBUSY while streaming
795bce4 media: ov772x: create subdevice device node
```

# Thank you for the attention

- Questions?

*This presentation was made with inkscape and LibreOffice: a big thanks to the developers of these two softwares!*



**Embedded Linux  
Conference**

Europe

---



**OpenIoT Summit**  
Europe