Real-Time is coming to Linux

What does that mean for you?

Steven Rostedt 10/24/2018



© 2016 VMware Inc. All rights reserved.

Who is this talk for?

- Linux kernel developers
 - Core kernel code
 - Driver code
 - File System code
 - Pretty much anyone touching the Linux Kernel
- Those that want to know why PREEMPT_RT makes Linux different

Who is this talk for?

- Linux kernel developers
 - Core kernel code
 - Driver code
 - File System code
 - Pretty much anyone touching the Linux Kernel
- Those that want to know why PREEMPT_RT makes Linux different
- Those that want to see how fast Steven talks in Real Time

• What is Real-Time?



vmware[®]

• What is Real-Time?

What is your favourite colour?

• What is Real-Time?

What is your favourite colour? **BLUE**

• What is Real-Time?

What is your favourite colour? no **RED!**



- What is Real-Time?
 - The term is ambiguous

- What is Real-Time?
 - The term is ambiguous
 - Top definition from http://urbandictionary.com

REAL TIME instantaneous; taking place at once as other things are also in progress. "When I surveyed the situation in real time, there were only 4 people who met the qualifications".

#instantaneous #simultaneously #survey #in progress #process
#momentary



- What is Real-Time?
 - The term is ambiguous
 - Top definition from http://WhatIs.com

REAL TIME is a level of computer responsiveness that a user senses as sufficiently immediate or that enables the computer to keep up with some external process.

- What is Real-Time?
 - The term is ambiguous
 - Top definition from http://WhatIs.com

REAL TIME is an adjective pertaining to computers or processes that operate in real time.

- What is Real-Time?
 - The term is ambiguous
 - Top definition from http://WhatIs.com

REAL TIME describes a human rather than a machine sense of time.

- What is Real-Time?
 - What does it mean as per PREEMPT_RT (aka "The Real-Time Patch")?

- What is Real-Time?
 - What does it mean as per PREEMPT_RT (aka "The Real-Time Patch")?
 - Means determinism
 - Has nothing to do with speed
 - Only latency
 - Can calculate worse case scenarios
 - Can determine what will happen
 - Can determine when it will happen

- What is Real-Time?
 - What does it mean as per PREEMPT_RT (aka "The Real-Time Patch")?
 - Means determinism
 - Has nothing to do with speed
 - Only latency
 - Can calculate worse case scenarios
 - Can determine what will happen
 - Can determine when it will happen
- Should be called a Deterministic Operating System



DOS!



- What's the strategy?
 - To make the kernel as preemptive as possible
 - Remove preemption and interrupt disabling
 - Where we can
 - Allow scheduling to happen (almost) everywhere!

- What's the strategy?
 - To make the kernel as preemptive as possible
 - Remove preemption and interrupt disabling
 - Where we can
 - Allow scheduling to happen (almost) everywhere!

Let the most important (highest priority) task run, when it wants to run.

• In "Processor type and features"





- In "Processor type and features"
 - "No Forced Preemption" CONFIG_PREEMPT_NONE
 - "Voluntary Kernel Preemption" CONFIG_PREEMPT_VOLUNTARY
 - "Preemptible Kernel (Low-Latency Desktop)" CONFIG_PREEMPT_LL
 - "Preemptible Kernel (Basic RT) CONFIG_PREEMPT_RTB
 - "Full Preemptible Kernel" CONFIG_PREEMPT_RT_FULL

- In "Processor type and features"
 - "No Forced Preemption" CONFIG_PREEMPT_NONE
 - "Voluntary Kernel Preemption" CONFIG_PREEMPT_VOLUNTARY
 - "Preemptible Kernel (Low-Latency Desktop)" CONFIG_PREEMPT_LL
 - "Preemptible Kernel (Basic RT) CONFIG_PREEMPT_RTB
 - "Full Preemptible Kernel" CONFIG_ PREEMPT_RT_FULL

- Interrupts as threads
 - requst_threaded_irq() Been in the kernel since 2009!
 - All interrupts as threads ("threadirqs") Been in the kernel since 2011
- Not all interrupts become Threads
 - IRQF_NO_THREAD
 - Timer Interrupts
 - IPI (Inter-Processor Interrupts)
 - IRQF_PERCPU
 - IRQF_ONESHOT

Interrupts

• Normal Interrupt

request_irq(unsigned int irq, irq_handler_t **handler**, unsigned long flags, const char *name, void *dev)



Interrupts

• Threaded Interrupt



Interrupts

• Forced Threaded Interrupts



- spin_lock*() becomes a mutex
 - Well, they are not really spinning locks anymore, are they?
 - They do not disable preemption
 - They do not disable interrupts (even spin_lock_irq*())

- spin_lock*() becomes a mutex
 - Well, they are not really spinning locks anymore, are they?
 - They do not disable preemption
 - They do not disable interrupts (even spin_lock_irq*())
 - How? Why?

Spin Locks



vmware[®]

Spin Locks



Spin Locks



vmware[®]

Priority Inheritance

- Prevents Priority Inversion
- Currently only implemented for futex (Fast User-space muTEX)
 pthread_mutexattr_setprotocol(&attr, PTHREAD_PRI0_INHERIT)
- PREEMPT_RT adds it to spin_locks() and mutex_lock()

Priority Inversion



vmware[®]

Priority Inheritance



vmware[®]

- rw_locks become more like rwsem
 - Sleepable reader / writer locks
- Readers DO NOT HAVE PRIORITY INHERITANCE!
- Writers do inherit priority
 - But they do not boost readers
- Try to avoid rw locks and sems
 - Horrible for cache lines (they do not scale)
 - Use RCU when you can

• The 'trylock' issue

```
again:
    spin_lock(&a);
    [..]
    if (!spin_trylock(&b)) {
        spin_unlock(&a);
        goto again;
    }
```

- The 'trylock' issue
- Works fine for spinning locks, but not for mutex

```
again:
    spin_lock(&a);
    [..]
    if (!spin_trylock(&b)) {
        spin_unlock(&a);
        goto again;
    }
```

Real Spinning Locks

vmware[®]





vmware[®]

• One solution that works when applicable

```
again:
  spin_lock(&a);
  Γ..]
  if (!spin_trylock(&b)) {
     spin_unlock(&a);
     spin_lock(&b);
     spin_unlock(&b);
     goto again;
```



vmware[®]

- Variables that are only accessed by their associated CPU
- Only need to disable preemption
- Spin Locks no longer disable preemption

- Variables that are only accessed by their associated CPU
- Only need to disable preemption
- Spin Locks no longer disable preemption

```
spin_lock(&mylock);
x = this_cpu_read(myX);
y = this_cpu_read(myY);
z = x + y;
this_cpu_write(myZ, z);
```

spin_unlock(&mylock);

- Variables that are only accessed by their associated CPU
- Only need to disable preemption
- Spin Locks no longer disable preemption
- Spin Locks do disable migration!

```
spin_lock(&mylock);
x = this_cpu_read(myX);
y = this_cpu_read(myY);
z = x + y;
this_cpu_write(myZ, z);
```

spin_unlock(&mylock);

- May be protected by spin locks
- May be protected by preempt_disable()
 NOT BOTH!

Task A

```
spin_lock(&mylock);
```

```
x = this_cpu_read(myX);
y = this_cpu_read(myY);
z = x + y;
this_cpu_write(myZ, z);
```

```
spin_unlock(&mylock);
```

Task B

```
preempt_disable();
```

```
x = this_cpu_read(myX);
y = this_cpu_read(myY);
z = x + y;
this_cpu_write(myZ, z);
```

preempt_enable();

spin_lock(&mylock);

```
Task A
          x = this_cpu_read(myX);
                                            schedule
           preempt_disable();
           x = this_cpu_read(myX);
           y = this_cpu_read(myY);
Task B
           z = x + y;
           this_cpu_write(myZ, z);
           preempt_enable();
                                            schedule
          y = this_cpu_read(myY);
          z = x + y;
Task A
          this_cpu_write(myZ, z);
          spin_unlock(&mylock);
```

- Preempt Disable is not bad
- If it is short!

preempt_disable(); x = this_cpu_read(myX); y = this_cpu_read(myY); z = x + y; this_cpu_write(myZ, z);

preempt_enable();



- Preempt Disable is not bad
- If it is short!
- Don't do THIS!

```
preempt_disable();
```

```
x = this_cpu_read(myX);
y = this_cpu_read(myY);
```

```
w = kmalloc(sizeof(*z), GFP_ATOMIC);
if (!w)
goto out;
```

```
z = x + y;
this_cpu_write(myZ, z);
w->foo = z;
```

out:
preempt_enable();



vmware[®]

- Preempt Disable is not bad
- If it is short!
- DO this!

```
w = kmalloc(sizeof(*z), GFP_KERNEL);
if (!w)
    return;
preempt_disable();
x = this_cpu_read(myX);
y = this_cpu_read(myY);
z = x + y;
this_cpu_write(myZ, z);
w->foo = z;
```

preempt_enable();



- Preempt Disable is not bad
- If it is short!
- DO this!

```
w = kmalloc(sizeof(*z), GFP_KERNEL);
if (!w)
    return;
preempt_disable();
x = this_cpu_read(myX);
y = this_cpu_read(myY);
z = x + y;
this_cpu_write(myZ, z);
w->foo = z;
```

preempt_enable();



- Preempt Disable is not bad
- If it is short!
- Keep slow operations OUT of preempt disable critical sections
 - This is good for PREEMPT_RT



- Preempt Disable is not bad
- If it is short!
- Keep slow operations OUT of preempt disable critical sections
 - This is good for PREEMPT_RT
 - This is good for mainline too!



Disabling interrupts

- Avoid local_irq_save()
 - Most likely it's a bug if you are using it
- Use spin_lock_irqsave() (or spin_lock_irq())
 - They disable interrupts on non PREEMPT_RT
 - They don't on PREEMPT_RT (that's what you want!)

Disabling interrupts

- Avoid local_irq_save()
 - Most likely it's a bug if you are using it
- Use spin_lock_irqsave() (or spin_lock_irq())
 - They disable interrupts on non PREEMPT_RT
 - They don't on PREEMPT_RT (that's what you want!)

NEVER DO! ...

local_irq_save(flags); spin_lock(&mylock);

or

spin_unlock(&mylock); local_irq_restore(flags);

- Are a real PITA
- They are "raised"
 - Asked to run
- Raised by interrupts
- Raised by tasks

- local_bh_disable() and spin_lock_bh()
 - **disables** preemption non PREEMPT_RT
 - preemption stays enabled on PREEMPT_RT
 - migration disabled

- Currently (in mainline)
 - Are indiscriminate in what they run
 - No priority between them
 - If one runs for a long time, no other one can run on that CPU
 - No priority between what takes precedence

- Currently (in mainline)
 - Are indiscriminate in what they run
 - No priority between them
 - If one runs for a long time, no other one can run on that CPU
 - No priority between what takes precedence
- In PREEMPT_RT
 - Runs by who raises them
 - A mask is used
 - local_bh_enable()
 - Runs the softirqs raised by the task
 - ksoftirq runs the rest of them

vmware

- Mainline is currently suffering from softirgs
 - Starvation of one softirq by another
 - Frederic Weisbecker has a patch set out to help
 - Influenced by the work from the PREEMPT_RT patch
 - Using a mask and also allow softirqs to preempt each other

softirqs NON_PREEMPT







raw_spin_locks

- raw_spin_lock*() is still a spinning lock
 - They were introduced in Linux in 2009 (2.6.33!)
 - They are meaningless in mainline
 - Were added for for PREEMPT_RT only!
- Makes order important
 - Can not call raw_spin_lock() followed by spin_lock()
 - Same as current spin_lock() followed by mutex_lock()

raw_spin_locks

- Used when you definitely CAN NOT SLEEP!
- Don't use them just because you can't "figure it out"
 - "scheduling while atomic"
 - Keep irq disabling short
 - Keep preempt disabling short
- Your lock is not as important as you think it is

